

CN Tower Lightning Return-Stroke Current Simulation

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Abstract: Different functions have been used to model the lightning return-stroke current with the aid of direct current measurements at tall structures. In this paper, a comparison between the Pulse function and Heidler function is carried out to find out the suitability of each of these functions for simulating the lightning return-stroke current, measured at the CN Tower. An automated system for determining the CN Tower lightning return-stroke current waveform parameters is introduced. The curve fitting technique of this system and the estimation of the initial values of the simulation function parameters are presented. An artificial lightning signal, free of noise and reflections, is used as a reference signal for evaluating the parameter extraction system. Finally, cumulative statistics of the CN Tower lightning return-stroke current waveform parameters (peak, maximum rate of rise, risetime, pulse width, decay time and charge) are derived using the Pulse function parameters.

Keywords: Lightning return stroke current, Heidler function, pulse function, CN tower, double exponential function.

1. INTRODUCTION

Heidler function and its modified form have been widely used to simulate the lightning return-stroke current [1-3]. Furthermore, the derivative of Heidler function and the derivative of its modified form have been successfully used to simulate the lightning return-stroke current derivative, measured at the Toronto CN Tower [4-6].

This paper presents an in-depth investigation of Heidler function and its derivative in order to evaluate its suitability to simulate the lightning return-stroke current and its derivative, respectively, especially for tall-structures where reflections from structural discontinuities play an important role in the simulation. As part of the evaluation of Heidler function, it is compared with other relevant functions, such as the pulse function.

In the past, many functions were considered for simulating the lightning return-stroke current [7-11]. Some of these functions were found to have problems related to their discontinuities or the discontinuities of their first and second derivatives at the onset time. Such problems appear in the double exponential function and its modifications (Jones [7], Gardner [8], etc). However, the Pulse function and Heidler function do not suffer from such problems [9].

One of the objectives of this work is to simulate the CN Tower lightning return-stroke current and its derivative using either Heidler function or the Pulse function and their derivatives, respectively. And although this work is fundamental for the evaluation and development of tall-structure lightning return-stroke modeling [4], it is necessary for the determination of all waveform parameters of the current measured at the CN Tower, including the charge.

For CN Tower lightning currents with high signal-to-noise ratios and fast rates of rise, it is possible to determine some of the current waveform parameters, namely the peak, the maximum rate of rise and the 10% to 90% risetime. However, other important current parameters, such as the pulse width, the decay time and the return-stroke charge, have been extremely difficult to determine because of current reflections resulting from the CN Tower's structural discontinuities, as well as the time-window limitation of the measured current derivative signal.

In this paper, all lightning return-stroke current waveform parameters are systematically obtained by, respectively, matching the simulation function or its derivative to the current or its derivative before the arrival of reflections.

The effectiveness of Heidler function or the Pulse function in simulating the CN Tower lightning current is evaluated by trying to fit each function to the current and determine the quality of the fit in each case.

2. SIMULATION FUNCTIONS

Both the Pulse and Heidler functions have the same general formulation that is based on the decoupling between a rise function $x(t)$ and a decay function $y(t)$. The rise and decay portions of a simulation function are chosen such that during the decay phase $x(t)=1$ and during the rise phase $y(t)=1$. The lightning return-stroke current simulation function is expressed in the form:

$$I(t) = I_{\max} x(t)y(t) \quad (1)$$

Since each of the rise function $x(t)$ and the decay function $y(t)$ is not actually unity during the decay phase and the rise phase, respectively, the lightning return-stroke current simulation function is modified to:

$$I(t) = \frac{I_{\max}}{\eta} x(t)y(t) \quad (2)$$

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2.1. The Pulse Function

The Pulse function is another function that is used to represent the lightning return-stroke current [3]. It is mathematically defined by:

$$I(t) = \frac{I_{max}}{\eta} \left(1 - e^{-\frac{t}{\tau_1}} \right)^n e^{-\frac{t}{\tau_2}} \quad (3)$$

$$\eta = \left(\frac{n\tau_2}{\tau_1 + n\tau_2} \right)^n \left(\frac{\tau_1}{\tau_1 + n\tau_2} \right)^{\frac{\tau_1}{\tau_2}} \quad (4)$$

While it's derivative is given by:

$$\frac{dI(t)}{dt} = I(t) \left[\frac{n}{\tau_1} \frac{e^{-\frac{t}{\tau_1}}}{\left(1 - e^{-\frac{t}{\tau_1}} \right)} - \frac{1}{\tau_2} \right] \quad (5)$$

The zero crossing time of the current derivative, which corresponds to the current maximum, t_{max} , is obtained from (5), when the current derivative vanishes.

$$t_{max} = \tau_1 \ln \left(1 + \frac{n\tau_2}{\tau_1} \right) \quad (6)$$

Also, the time of occurrence of the maximum steepness t_{ms} of the function is a very important current waveform parameter. By equating the second derivative of the Pulse function to zero we get:

$$\left(\frac{n}{\tau_1} \right)^2 e^{-\frac{2t_{ms}}{\tau_1}} + \frac{\left(1 - e^{-\frac{t_{ms}}{\tau_1}} \right)^2}{\tau_2^2} - \frac{n}{\tau_1^2} e^{-\frac{t_{ms}}{\tau_1}} - \frac{2ne^{-\frac{t_{ms}}{\tau_1}}}{\tau_1\tau_2} \left(1 - e^{-\frac{t_{ms}}{\tau_1}} \right) = 0 \quad (7)$$

Equation (7) can be analytically solved to determine the time of occurrence of the current maximum steepness, t_{ms} . Since t_{ms} takes place during the rising phase of the current where the decay portion $y(t) \approx 1$, then the Pulse function can be approximated during the rising phase as:

$$I(t) = \frac{I_{max}}{\eta} \left(1 - e^{-\frac{t}{\tau_1}} \right)^n \quad (8)$$

Using the second derivative and equating it to zero then a general form for t_{ms} can be obtained:

$$t_{ms} = \tau_1 \ln(n) \quad (9)$$

2.2. Heidler Function

Heidler function is defined as:

$$I(t) = \frac{I_{max}}{\eta} \frac{\left(\frac{t}{\tau_1} \right)^n}{1 + \left(\frac{t}{\tau_1} \right)^n} e^{-\frac{t}{\tau_2}} \quad (10)$$

$$\eta = e^{-\left(\frac{\tau_1}{\tau_2} \sqrt{\frac{n\tau_2}{\tau_1}} \right)} \quad (11)$$

While its derivative is:

$$\frac{dI(t)}{dt} = I(t) \left[\frac{n}{t} - \frac{1}{\tau_2} - \frac{nt^{n-1}}{\left(\tau_1^n + t^n \right)} \right] \quad (12)$$

For Heidler function, the zero crossing of the current derivative t_{max} is obtained numerically by solving the following equation:

$$\frac{t_{max}^{n+1}}{\tau_1^{n+1}} + \frac{t_{max}}{\tau_1} = \frac{n\tau_2}{\tau_1} \quad (13)$$

An approximate estimation of t_{max} can be determined by assuming that $n \gg 1$ and $(t_{max} / \tau_1) \gg 1$. In this case, we can ignore (t_{max} / τ_1) with respect to $(t_{max} / \tau_1)^{n+1}$ and thus t_{max} can be put in the form:

$$t_{max} = \tau_1 \sqrt[n+1]{\frac{n\tau_2}{\tau_1}} \quad (14)$$

Also, the time of occurrence of the maximum steepness t_{ms} of the derivative of Heidler function is obtained by equating the second derivative of Heidler function to zero producing equation (15)

$$\frac{n}{t_{ms}} \left(\frac{n-1}{t_{ms}} - \frac{2}{\tau_2} \right) - \frac{nt_{ms}^{n-1}}{\left(\tau_1^n + t_{ms}^n \right)} \left(\frac{3n-1}{t_{ms}} + \frac{2}{\tau_2} \right) + \frac{1}{\tau_2^2} = 0 \quad (15)$$

The maximum steepness time t_{ms} occurs during the rising phase of the current, where the decay phase function $y(t) \approx 1$, thus Heidler function, at the rising phase, can be approximated to:

$$I(t) = \frac{I_{max}}{\eta} \frac{\left(\frac{t}{\tau_1} \right)^n}{1 + \left(\frac{t}{\tau_1} \right)^n} \quad (16)$$

Equating the second derivative of Heidler function to zero, a general expression for t_{ms} can be determined:

$$t_{ms}^n = \frac{\tau_1^n (n-1)}{(n+1)} \quad (17)$$

3. INTIAL VALUE ESTIMATION

In order to reach the optimal values of the simulation function parameters, the initial value estimation of these parameters need to be estimated. The impact of the initial condition on the curve fitting technique can be investigated by creating an artificial noise-free signal that resembles the measured signal before being corrupted by reflections. This artificial signal can be produced by having a signal source represented by an analytical function, such as Heidler function or the Pulse function. Setting the parameters of this artificial analytical function produces a continuous

waveform. Then, this waveform is made to pass through a software digitizer having the same time resolution of the lightning current derivative recording system, which results in an artificial digital signal that simulates the measured signal.

Heidler function's analytical parameters are I_{max} , τ_1 , τ_2 and n , which are also the parameters of the Pulse function. In both cases, the initial value of I_{max} is known from the measurement as the maximum value of the current signal.

The decoupling behaviour of the Pulse function is used to separate the initial value estimation of τ_2 from other parameters. This can be done by estimating the initial value of τ_1 and n using the approximation given by (8).

Although the value of I_{max} is known from the measurement, two points of the data are enough for calculating τ_1 and n , but for better accuracy three points are used to eliminate I_{max} and η from the equations. These three points are chosen based on the explained criterion to form:

Pulse Function	$\frac{\ln\left(\frac{I(t_1)}{I(t_2)}\right)}{\ln\left(\frac{I(t_2)}{I(t_3)}\right)} = \frac{\ln\left(\frac{1-e^{-\frac{t_1}{\tau_1}}}{1-e^{-\frac{t_2}{\tau_1}}}\right)}{\ln\left(\frac{1-e^{-\frac{t_2}{\tau_1}}}{1-e^{-\frac{t_3}{\tau_1}}}\right)}$	(18)	Heidler Function	$\frac{1-\frac{I(t_3)}{I(t_2)}}{1-\frac{I(t_1)}{I(t_2)}} = \frac{1-\frac{I(t_3)}{I(t_2)}\left(\frac{t_2}{t_3}\right)^n}{1-\frac{I(t_1)}{I(t_2)}\left(\frac{t_2}{t_1}\right)^n}$	(20)
	$n = \frac{\ln(I(t_1)) - \ln(I(t_2))}{\ln\left(1 - e^{-\frac{t_1}{\tau_1}}\right) - \ln\left(1 - e^{-\frac{t_2}{\tau_1}}\right)}$	(19)		$\tau_1 = \sqrt[n]{\frac{I(t_2) - I(t_1)}{\frac{I(t_1)}{t_1^n} - \frac{I(t_2)}{t_2^n}}}$	(21)

Using the same procedure for finding τ_2 by applying the current functions on two data points where the locations of the data points satisfy the condition that their time of occurrences are greater than the time of occurrence of the maximum current so that the rising portion of the function $x(t) \approx 1$, then we divide the two equation formed using the data points to eliminate I_{max} and η .

$$\tau_2 = \frac{t_5 - t_4}{\ln\left(\frac{I(t_4)}{I(t_5)}\right) - n \ln\left(\frac{1 - e^{-\frac{t_4}{\tau_1}}}{1 - e^{-\frac{t_5}{\tau_1}}}\right)} \tag{22}$$

The approximation made proved to be very efficient in the determination of the initial values of the parameters. It was concluded that the simulation of the current derivative yield closer fit to the measurement, when compared with the fit resulting from simulating the current [12].

4. CURVE FITTING PROCESS

The curve fitting technique used in this paper utilizes the least square method. It is an approach that minimizes the sum of the squares of the residuals between the measured data points and the calculated ones. This method is usually used when the data exhibit significant degree of error or noise; in this case the strategy is to derive a curve that represents the general trend of the data.

The lightning current derivative signal measured at the CN Tower exhibits different kinds of noise, including those produced by equipment-limited resolution and reflections [13]. Current reflections resulting from CN Tower structural discontinuities are the major cause of distortion to the lightning return-stroke current, normally injected at the tip of the Tower. For example, as shown in Fig. (1), the ground reflection produces major peaks in the current and the current derivative waveforms after 3.2 μs from initial peaks. Therefore, it is necessary when evaluating the quality of the curve fitting to use some guidelines together with R^2 (Mean Square Error) in order to seek the optimal solution. These guidelines may include the time location of the current

wavefront maximum steepness and the current derivative zero crossing, which corresponds to the location when the current reaches its maximum value.

Applying the explained curve fitting technique on the measured current derivative using both simulating functions, a comparison between the quality of fit using the Pulse function and Heidler function can be performed.

Using the curve fitting process, Figs. (1, 2) show that the guidelines for judging the best fit to the measured signal for both functions have not been achieved. The decay portion of the simulated current is consistently lower than the measured current. The preliminary result showed that a major improvement of the simulation was necessary.

4.1. Estimation of τ_2

As mentioned before, the structure of Heidler function and the Pulse function is composed of the rise portion $x(t)$ and the decay portion $y(t)$. By studying the effect of the rise term $x(t)$ on each of the simulation functions during the

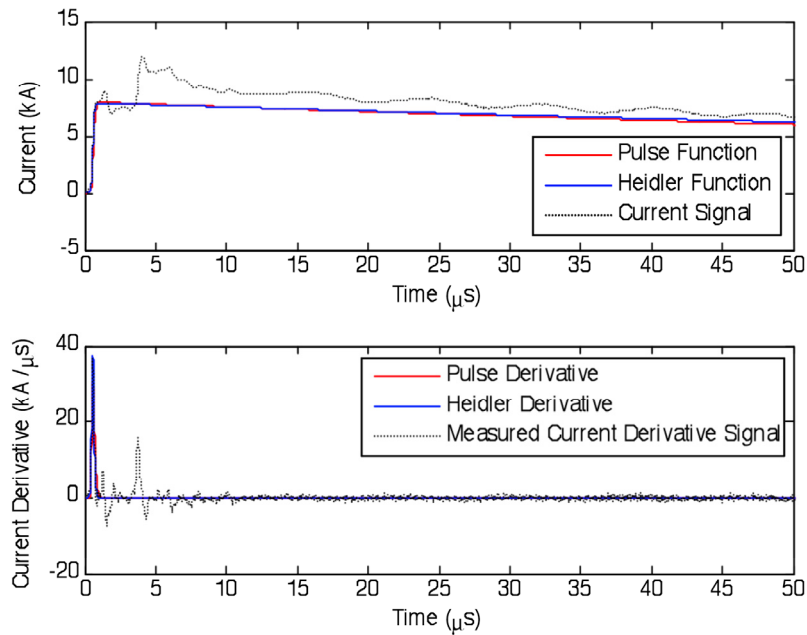


Fig. (1). Curve fitting results using the Pulse and Heidler function for simulating the measured current derivative.

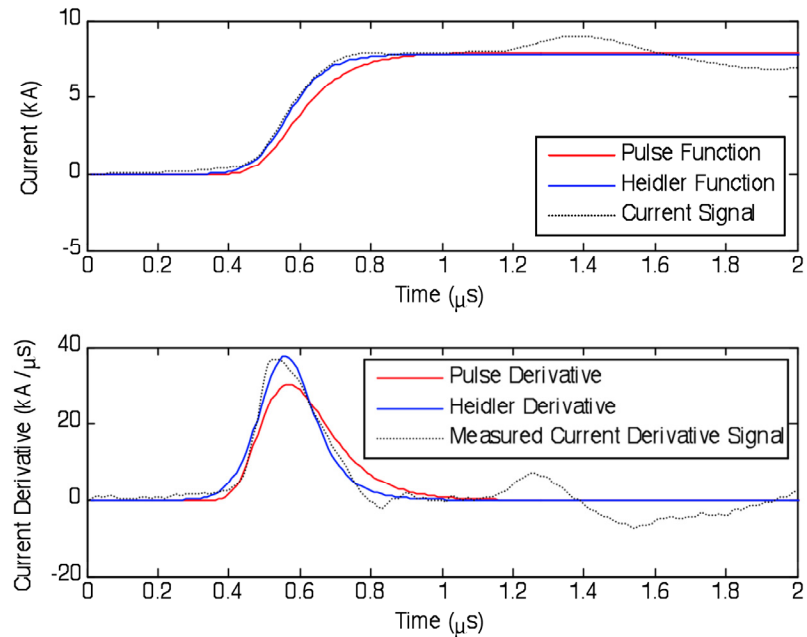


Fig. (2). Zoomed curve fitting results using the Pulse and Heidler functions for simulating the measured current derivative.

decay of the signal, when $t \gg \tau_1$, it is found that both functions are insensitive to the rise term where $x(t) \approx 1$ and therefore, the decay portion becomes dominant for both Heidler and the Pulse functions. In this range, both functions take the form:

$$I(t) = Ae^{-\frac{t}{\tau_2}} \tag{23}$$

Also, its derivative will have the form:

$$\frac{dI(t)}{dt} = -\frac{A}{\tau_2} e^{-\frac{t}{\tau_2}} \tag{24}$$

In order to obtain τ_2 separately, the measured current derivative signal and its corresponding current, obtained by numerical integration, are divided each into three time-windows. The first time-window represents the initial impulse before the arrival of reflections. The second time-window includes the early decaying part of the waveform, which contains reflections. Finally, the third time-window represents the decay, where the waveform is less affected by reflections in comparison with its behaviour within the second time-window. The application of the curve fitting technique on the current waveform within the third time-window, which is represented by an exponentially decaying

function, equation (23), results in a good estimate of the decay time parameter, τ_2 .

It is important to point out that the current is used in the fitting technique to estimate τ_2 rather than the measured current derivative signal. Within the decay time-window, the measured current derivative has a substantially lower signal-to-noise ratio because of its high frequency noise, when compared with the current (see Figs. 1, 2), which leads to the failure of the fitting process.

By estimating τ_2 , the parameters of the simulation function are reduced to only three parameters, namely, τ_1 , n and I_{max} . Therefore, the estimation of the decay-time parameter will be always the first step in the curve fitting process of both the Pulse and Heidler functions.

The results of applying the above mentioned curve fitting technique on the current are shown in Figs. (3, 4). It is noted that the rate of decay of the simulated current becomes clearly closer to that of the measured current by the first

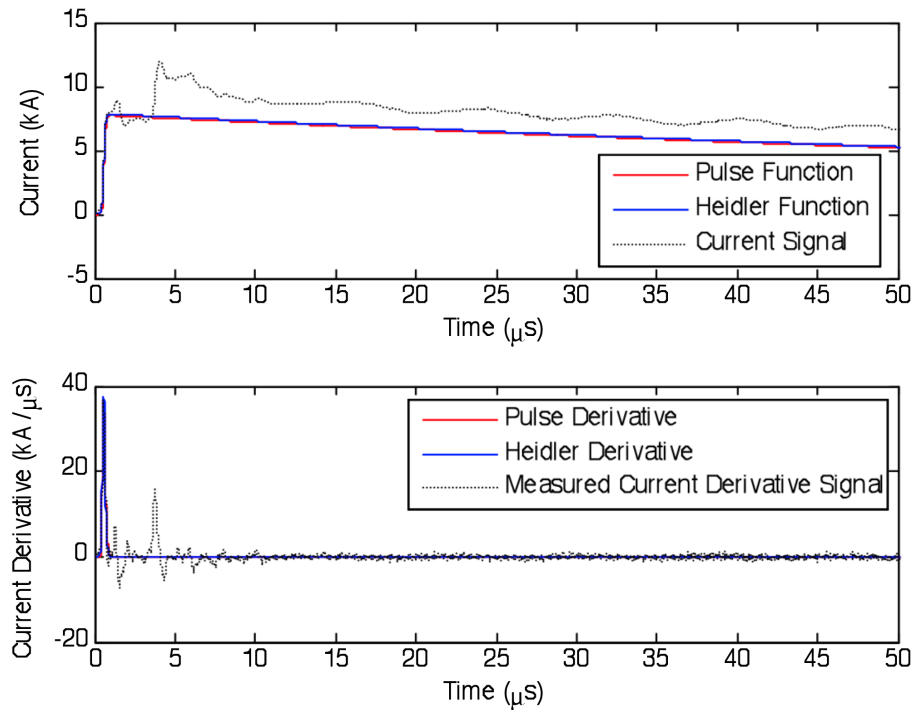


Fig. (3). Fitting results using the Pulse and Heidler functions for simulating the measured current derivative.

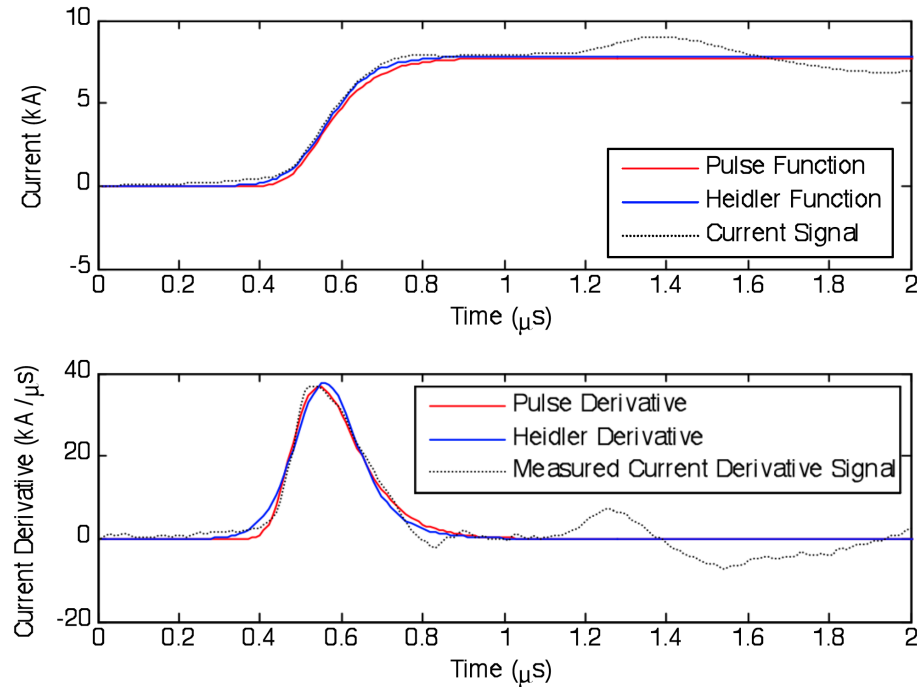


Fig. (4). Zoomed fitting results using the Pulse and Heidler functions for simulating the measured current derivative.

estimating the decay time parameter before the application of the curve-fitting technique (see Figs. 1, 3). Furthermore, a general comparison, within the first time-window, between the simulated current, using the new technique (Fig. 4), and that using the ordinary technique (Fig. 2), reveals a substantial improvement in the simulation. Similarly, the simulated current derivative using the new technique is markedly improved (Figs. 2, 4).

In case of the Pulse function, the current derivative fitting is achieved while the corresponding current experienced intolerable error within the maximum current and its time of occurrence. For Heidler function, although the current derivative fitting is not as good as obtained in case of the Pulse function but the corresponding current is much better than that of the Pulse function, however, the maximum current and its time of occurrence were not achieved as well.

Since the maximum current value is a common problem it can be adjusted by forcing the maximum current I_{max} to have a certain value. This value can be obtained by visual investigation of the integration of the measured current derivative signal. By assigning the value of I_{max} , the number of analytical parameters will be reduced to two, namely, n and τ_1 .

As shown in Fig. 5, the Pulse function current signal is improved while the maximum steepness value, the time of occurrence of the maximum steepness and the zero crossing of the current derivative need to be improved to best fit the measured signal. Heidler function will have the same problems encountered using the Pulse function.

4.2. Constraints

Another way for improving the simulation is by introducing a constraint to force the analytical parameters to reach their optimal values. This constraint is applied by

adjusting either the time of occurrence of the zero crossing of the current derivative or the time of occurrence of the maximum steepness of the current to a known value. We refer to these constraints in the paper as time-forcing constraints.

Applying this constraint using the known values of τ_2 and I_{max} , which were previously determined, τ_1 can be expressed in terms of n or vice versa. Accordingly, the number of analytical parameters of the functions will be reduced to one.

4.2.1. Zero Crossing

Firstly, the time forcing constraint will be applied to adjust the zero crossing of the current derivative to its measured value. In the case of the Pulse function, applying the constraint using equation (6), n can be expressed in terms of τ_1 . By substituting n in the Pulse function equation (3) and its derivative, equation (5), the only unknown parameter will be τ_1 . The function and its derivative can be reformatted as follows:

$$I(t) = \frac{I_{max}}{\eta} e^{-\frac{t}{\tau_2}} \left(1 - e^{-\frac{t}{\tau_1}} \right)^{\frac{\tau_1}{\tau_2} \left(e^{\frac{t_{max}}{\tau_1}} - 1 \right)} \tag{25}$$

$$\frac{dI(t)}{dt} = \frac{I_{max}}{\eta} e^{-\frac{t}{\tau_2}} \left(1 - e^{-\frac{t}{\tau_1}} \right)^{\frac{\tau_1}{\tau_2} \left(e^{\frac{t_{max}}{\tau_1}} - 1 \right)} * \left[\frac{\left(e^{\frac{t}{\tau_1}} - 1 \right) e^{-\frac{t}{\tau_1}}}{\tau_2 \left(1 - e^{-\frac{t}{\tau_1}} \right)} - \frac{1}{\tau_2} \right] \tag{26}$$

In the case of Heidler function, applying the constraint using equation (14), τ_1 can be expressed in terms of n . By

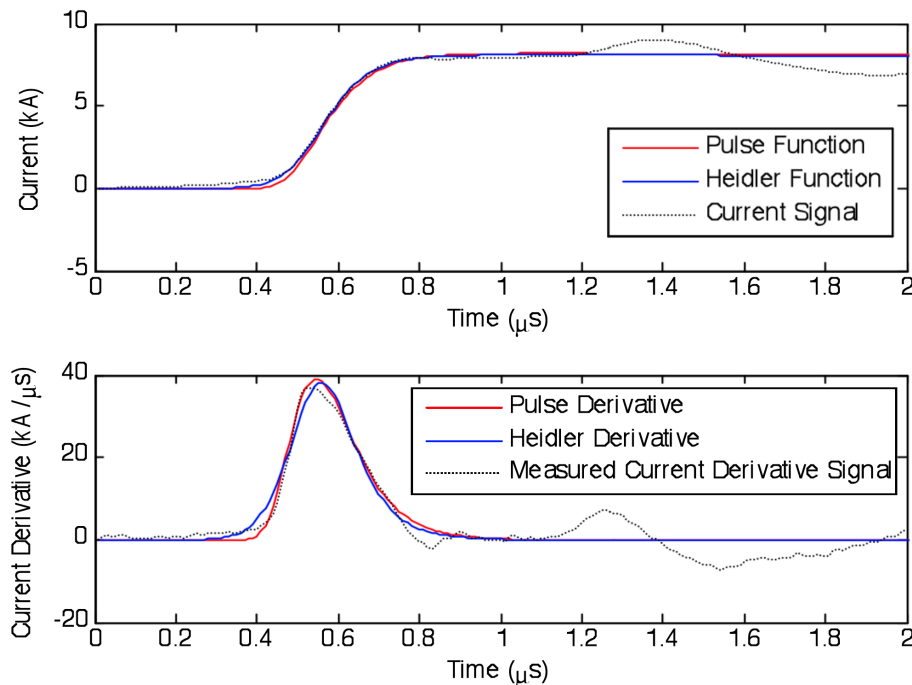


Fig. (5). Fitting result using the Pulse and Heidler functions for the measured current derivative with fixed τ_2 and I_{max} .

substituting n in Heidler function, equation (10), and its derivative, equation (12), the only unknown parameter will be n . The function and its derivative can be reformatted as follows:

$$I(t) = I_{\max} \frac{t^n \left(1 + \left(\frac{t_{\max}}{t_{ms}} \right)^n \frac{n-1}{n+1} \right) e^{-\frac{t-t_{\max}}{\tau_2}}}{t_{\max}^n \left(1 + \left(\frac{t}{t_{ms}} \right)^n \frac{n-1}{n+1} \right)} \quad (27)$$

$$\frac{dI(t)}{dt} = I_{\max} \frac{t^n \left(1 + \left(\frac{t_{\max}}{t_{ms}} \right)^n \frac{n-1}{n+1} \right) e^{-\frac{t-t_{\max}}{\tau_2}}}{t_{\max}^n \left(1 + \left(\frac{t}{t_{ms}} \right)^n \frac{n-1}{n+1} \right)} * \left[\frac{n}{t} - \frac{1}{\tau_2} - \frac{nt}{\left(\frac{t_{ms}^n (n+1)}{n-1} + t^n \right)} \right] \quad (28)$$

$$\left[\frac{n}{t} - \frac{1}{\tau_2} - \frac{nt}{\left(\frac{t_{ms}^n (n+1)}{n-1} + t^n \right)} \right]$$

Fig. (6) shows that an overshoot for the maximum steepness value of the current signal occurred leading to a very fast current rise. Consequently, the zero crossing constraint was not able to achieve the optimal value of the analytical parameters.

4.2.2. Maximum Steepness

Secondly, the time forcing constraint will be applied to adjust the maximum steepness of the current signal to its measured value. In the case of the Pulse function, applying the constraint using equation (9), n can be expressed in

terms of τ_1 . By substituting n in the Pulse function, equation (3), and its derivative, equation (5), the only unknown parameter will be τ_1 . The function and its derivative can be reformatted as follows:

$$I(t) = \frac{I_{\max}}{\eta} \left(1 - e^{-\frac{t}{\tau_1}} \right)^{\frac{t_{ms}}{\tau_1}} e^{-\frac{t}{\tau_2}} \quad (29)$$

$$\frac{dI(t)}{dt} = \frac{I_{\max}}{\eta} \left(1 - e^{-\frac{t}{\tau_1}} \right)^{\frac{t_{ms}}{\tau_1}} * \left[\frac{e^{-\frac{t_{ms}-t}{\tau_1}}}{\tau_1 \left(1 - e^{-\frac{t}{\tau_1}} \right)} - \frac{1}{\tau_2} \right] e^{-\frac{t}{\tau_2}} \quad (30)$$

Similarly, in the case of Heidler function, applying the constraint using equation (17), τ_1 can be expressed in terms of n . By substituting n in Heidler function, equation (10), and its derivative, equation (12), the only unknown parameter will be n . The function and its derivative can be reformatted as follows:

$$I(t) = \frac{I_{\max}}{\eta} \frac{\left(\frac{t}{t_{ms}} \right)^n \frac{n-1}{n+1} e^{-\frac{t}{\tau_2}}}{1 + \left(\frac{t}{t_{ms}} \right)^n \frac{n-1}{n+1}} \quad (31)$$

$$\frac{dI(t)}{dt} = \frac{I_{\max}}{\eta} \frac{\left(\frac{t}{t_{ms}} \right)^n \frac{n-1}{n+1} e^{-\frac{t}{\tau_2}}}{1 + \left(\frac{t}{t_{ms}} \right)^n \frac{n-1}{n+1}} * \left[\frac{n}{t} - \frac{1}{\tau_2} - \frac{nt^{n-1}}{\left(\frac{t_{ms}^n (n+1)}{n-1} + t^n \right)} \right] \quad (32)$$

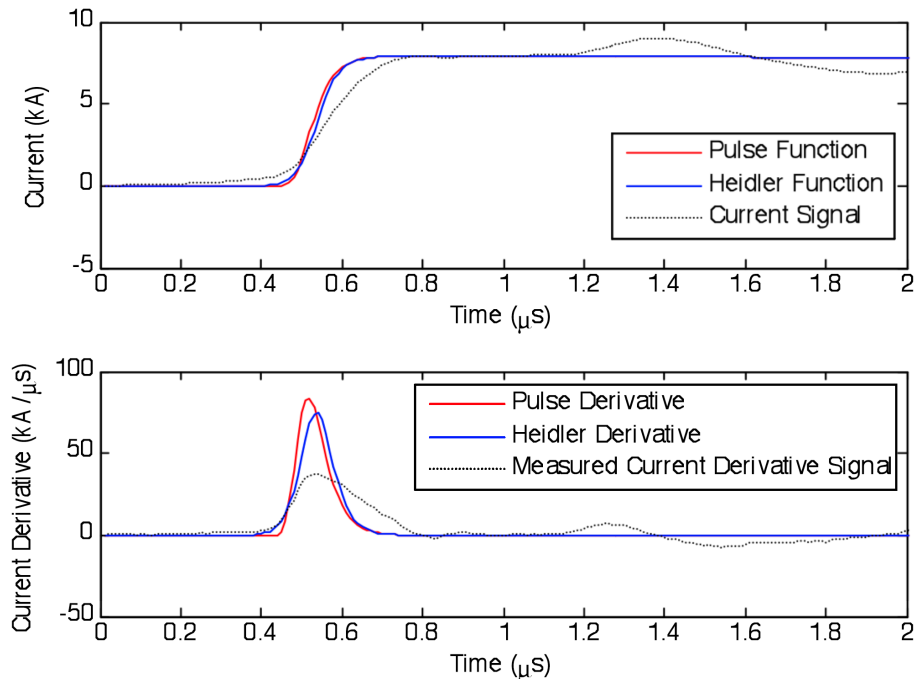


Fig. (6). Zoomed fitting results using the Pulse and Heidler functions for simulating the measured current derivative with fixed τ_2 and I_{\max} and with forcing the time occurrence of the zero crossing of the current derivative signal.

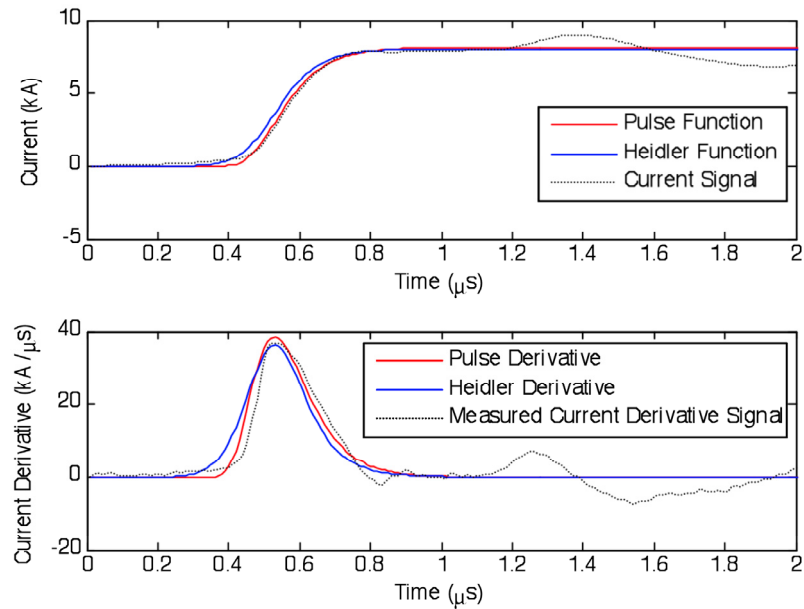


Fig. (7). Zoomed fitting results using the Pulse and Heidler functions for simulating the measured current derivative with fixed τ_2 and I_{max} and with forcing the time of occurrence of the maximum steepness of current signal.

Forcing the constraint regarding the time occurrence of the maximum steepness achieves the best fit for both simulating functions as shown in Fig. (7).

The described fitting process represents the best method to reach the optimal value for simulating the measured signal. Not only fitting the full measured signal including the decay part but also calculating all current waveform parameters can be achieved. Table 1 compares the current waveform parameters extracted manually from the measured signal and the ones calculated using the this fitting process for the pulse function. Using this fitting process for the Pulse function all current waveform parameters can be calculated and full statistics of this parameters can be built through which lightning protection can be done.

Table 1. Comparison Between Measured and Calculated Current Waveform Parameters

	Measured Signal	Pulse Function
Maximum Current (kA)	7906.5	7906.5
Maximum Steepness (kA/μs)	36.98	38.5735
Rise Time (μs)	0.25	0.2343
Decay Time (μs)	-----	285.97
Charge Transferred (C)	-----	0.9393
Waveform width half of maximum current (μs)	-----	89.204

It is very important to clarify that the better accuracy and the easiness achieved when using the simulated function to get the value of the current wave form parameters than using the traditional manual methods. Using the simulating function gave more freedom for calculating other parameters that was difficult to measure using the manual methods such as the decay time, charge being transferred and the wave form width for half maximum current.

5. CUMULATIVE STATISTICAL DISTRIBUTION

The described fitting process is applied on 15 flashes, containing 31 return strokes. The calculated current waveform parameters were used to form statistics to determine the probability distribution of the value of each parameter, including the range and the 50% probability level, which is fundamental in building lightning protection systems.

5.1. Current Peak

The cumulative distribution of the current peak of the lightning return-stroke current for the analyzed signals is shown in Fig. (8). The current peak, determined from the simulated function, varies from a minimum value of 2.59 kA to a maximum value of 11.08 kA. The average value of the current peak was found to be 5.57 kA. It was observed that in 50% of the recorded lightning strokes, the current peak exceeded 5.73 kA, in 5% of recorded signals, the current peak exceeded 10.21 kA and in 95% of captured strokes the current peak exceeded 2.98 kA.

5.2. Maximum Steepness

For the maximum steepness, its cumulative distribution is shown in Fig. (9). The lightning signals analyzed had a minimum value of 11.65 kA/μs and maximum value of 54.68 kA/μs for the maximum steepness. The average value for the maximum steepness was found to be 31.33 kA/μs. In 95% of the signals, the maximum steepness came to be higher than 14.31 kA/μs and in 5% of the cases the maximum steepness was higher than 51.21 kA / μs. The 50% probability value for the maximum steepness was found to be 34.31 kA/μs.

5.3. Rise Time to the Current Peak

The 10% to 90% risetime to the current peak for each of the analyzed signals was determined from the simulated

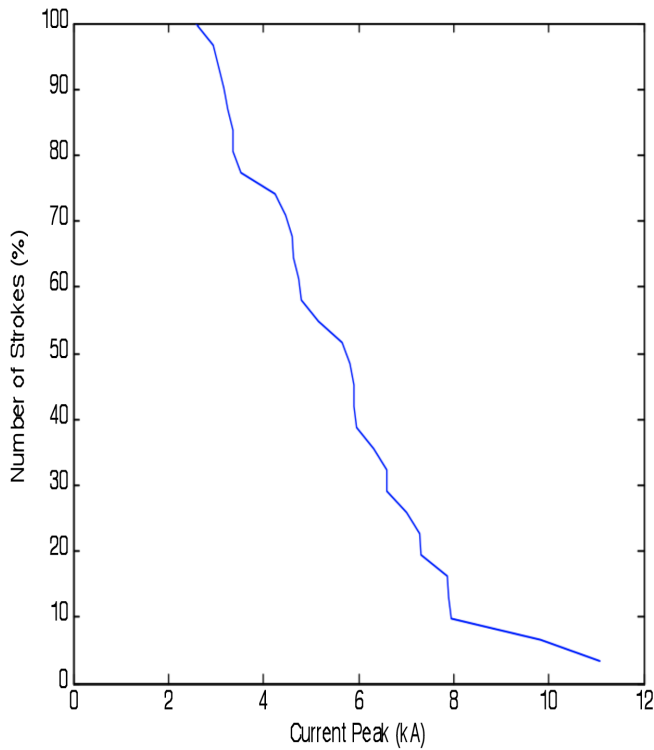


Fig. (8). Cumulative distribution of the current peak.

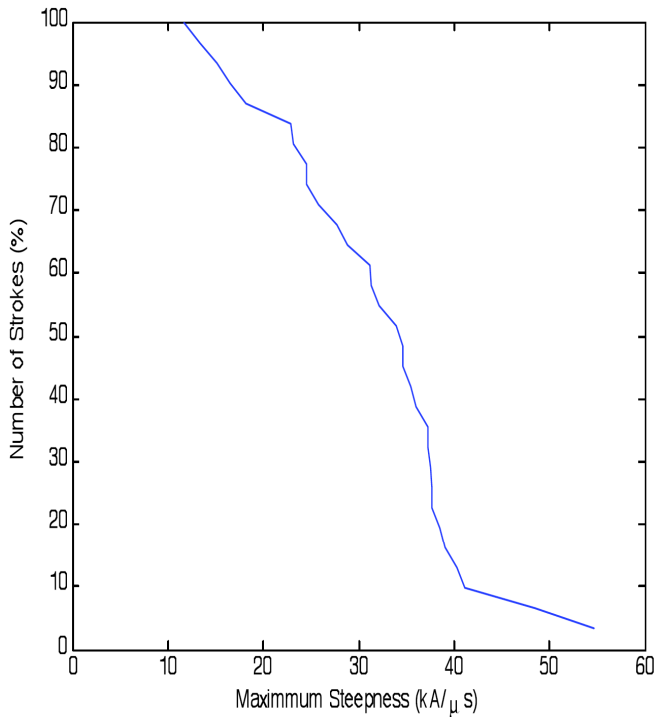


Fig. (9). Cumulative distribution of the maximum steepness.

function. Fig. (10) shows the cumulative distribution of the current risetime. The minimum recorded risetime to the current peak was 124 ns while the maximum recorded value was 524 ns with an average of 242.3 ns. It is important realize this large range of variation in the current risetime when designing lightning protection systems. For the analyzed signals, the current risetime exceeds 143 ns, 211 ns and 481 ns in 95%, 50% and 5% of the cases, respectively.

5.4. Decay Time from the Current Peak

The decay time of the current peak is an important waveform parameter. The 90% to 10% current decay time from the current peak for each of the analyzed signals was determined. The cumulative distribution of the current decay time is shown in Fig. (11). The minimum value of the current decay time was found to be 65.88 μs with maximum value of 537.13 μs. The average value of the current decay time is 255.64 μs. In 95% of the cases, the current decay time exceeds 75.26 μs and in 5% of the cases, it exceeds 523.6 μs. The 50% probability value of the current decay time is 261.3 μs.

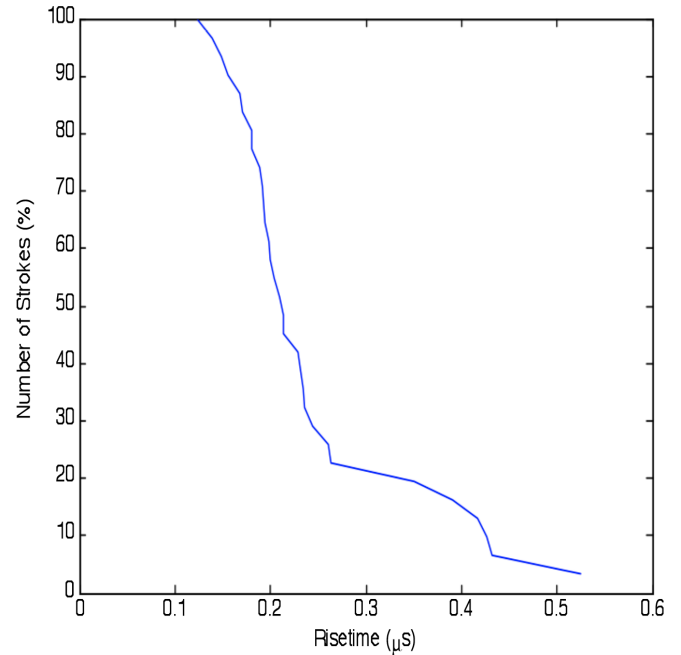


Fig. (10). Cumulative distribution of the risetime to the current peak.

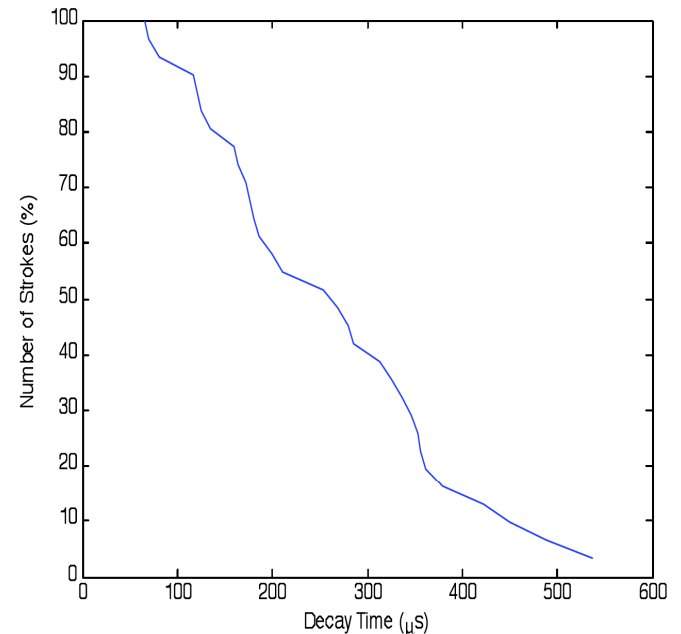


Fig. (11). Cumulative distribution of the decay time from the current peak.

5.5. Current Pulse Width

The current pulse width at the half current peak level for each of the analyzed signals was calculated by determining the time difference between the time at the 50% level of current peak at the decay side of the current pulse and the 50% level of the current peak at the rising side of the current pulse. Fig. (12) shows the cumulative distribution of the current pulse width. The minimum recorded current pulse width is 21.47 μs and the maximum recorded value is 157.51 μs , with an average of 83.99 μs . The large range of variation in current pulse width is important to take into consideration by engineers working on lightning protection methods. For the analyzed signals, the current pulse width 75.23 μs , 261.3 μs and 512.3 μs in 95%, 50% and 5% of the cases, respectively.

5.6. Charge

The charge is one of the most important waveform parameters in the area of protection. The charge for each of the analyzed signals was obtained by integrating the current. The cumulative distribution of the charge is shown in Fig. (13). The minimum value of the charge is 0.1187 C, while the maximum value is 1.897 C. The average value of the charge is 0.6642 C. In 95% of the cases, the charge exceeds 0.154 C and in 5% of the cases, the charge exceeds 1.671 C. In 50% of the analyzed signals, the charge exceeds 0.599 C.

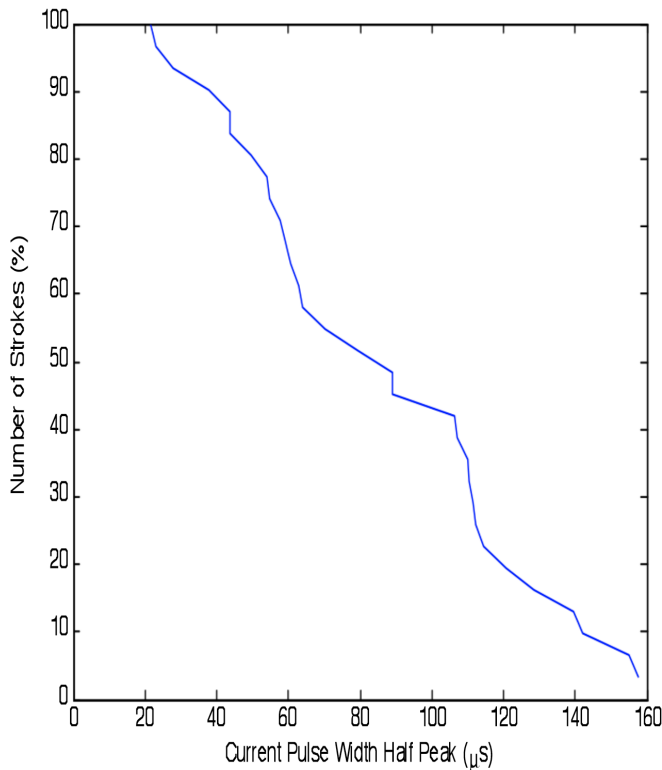


Fig. (12). Cumulative distribution of the current pulse width.

Table 2 summarizes the cumulative statistics of current waveform parameters, including each waveform parameter value at 95%, 50% and 5% of the cases. Also, it includes the maximum value, the minimum value, and the average value of each waveform parameters.

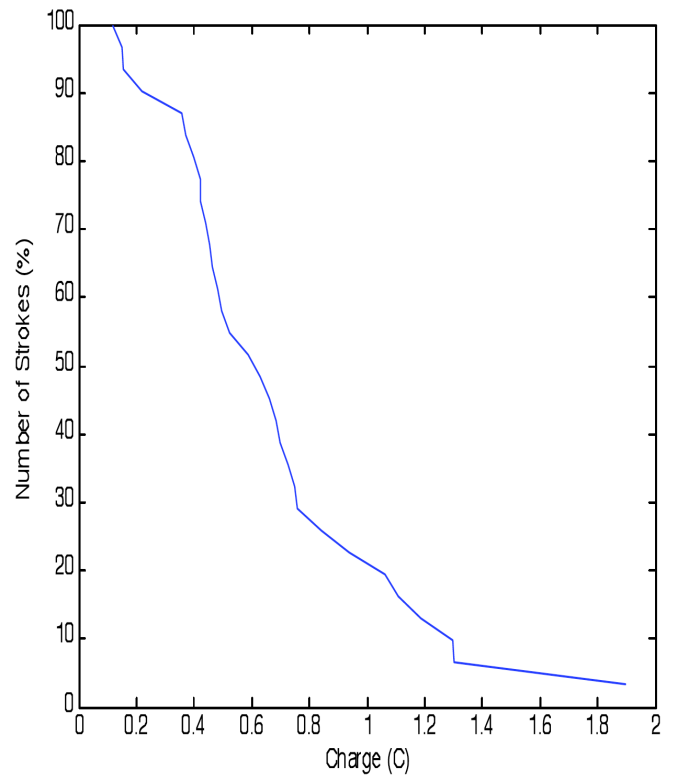


Fig. (13). Cumulative distribution of the charge.

6. CONCLUSIONS

From the previous results, it can be generally concluded that the simulation of the current derivative yields closer fit to the measurement, when compared with the fit resulting from simulating the current. Using artificial signals, which are free of noise and reflections, proved to be very efficient in the determination of initial value estimation.

The decoupling behaviour of the Pulse and Heidler functions helped in dividing the signal into three parts and avoiding the use of the second part, which is highly distorted by reflections, in the fitting process. The third part was used for estimating the decay parameter τ_2 . The first part (mainly the rise portion of the signal) was used to estimate the other parameters. Using the approximation of the decaying part for the simulating functions lead to same value of τ_2 and I_{max} for both functions.

Finally, using the time-forcing constraint for the maximum steepness of the current for fitting the rising part of the signal, given τ_2 and I_{max} , reduced the fitting process to a single-parameter estimation, and allowed the comparison between the Pulse function and Heidler function for simulating the measured. Although Heidler function is widely used in fitting the return-stroke current signal, the Pulse function proved to be a better fit for the lightning return-stroke current, measured at the CN Tower. The Pulse function is used to calculate the waveform parameters that were manually determined. Also, other important parameters that could not be determined previously were systematically computed. Newly determined parameters are the pulse width at half peak level, decay time, charge being transferred.

Table 2. Summary of the Cumulative Statistics of the Current Waveform Parameters

Waveform Parameter	Minimum	Maximum	Average	5%	50%	95%
Current Peak (kA)	2.895	11.08	5.572	10.21	5.73	2.98
Maximum Steepness (kA/ μ s)	11.65	54.68	31.3261	51.21	34.31	14.31
Risetime to Current Peak (μ s)	0.124	0.524	0.2423	0.481	0.211	0.143
Decay Time from current peak (μ s)	65.88	537.13	255.64	523.6	261.3	75.26
Current Pulse Width (μ s)	21.47	157.51	83.99	512.3	261.3	75.23
Charge (C)	0.1187	1.897	0.6642	1.671	0.5986	0.1542

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CONFLICT OF INTEREST

The authors confirm that this article content has no conflicts of interest.

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