

Evolution of the Motion Around a Slowly Rotating Body

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Abstract: The motion of a satellite about a rotating triaxial body will be investigated, stressing on the case of slow rotation. The Hamiltonian of the problem will be formed including the zonal harmonic J_2 and the leading tesseral harmonics C_{22} and S_{22} . The small parameter of the problem is the spin rate (σ) of the primary. The solution proceeds through three canonical transformations to eliminate in succession; the short, intermediate and long-period terms. Thus secular and periodic terms are to be retained up to orders four and two respectively.

Keywords: Hamiltonian, perturbation, motion, satellite.

1. INTRODUCTION

To understand the dynamics of a spacecraft or a natural particle around a celestial body (a planet, an asteroid or even a comet) it's convenient to take into account the spin rate (σ) of the primary, since it is important for several applications especially for geodetic satellites and when dealing with communication satellites where there's commensurability between the satellite period and σ , and a case of resonance arises [1-3]. Considering a slowly rotating earth like planet, the addition of tesseral harmonics is necessary [4, 5] analyzed the orbital dynamics about an asteroid and established that the major perturbations acting on the orbiter are due to the leading harmonics of the geopotential. In a subsequent work [6] he tackled the problem of secular motion in a 2nd degree and order-gravity field with no rotation qualitatively. In this respect the main problem of artificial satellite theory is very useful; the major contributors to this subject were [7-10] formed the Hamiltonian of the motion of an A.S. about a planet with an inhomogeneous gravitational field including the leading zonal and tesseral harmonics. He used the Whittaker variables and then he normalized the Hamiltonian using the method of elimination of the parallax developed by [11].

Instead of obtaining an explicit solution of the problem he performed an exhaustion analysis of the problem. The method adopted by Palacian, through elegant, but is very difficult to include higher order terms and higher order gravity coefficients.

In this paper the gravitational force exerted by an earth like planet on an artificial satellite will be considered, the Hamiltonian of the problem will be formed, in terms of the Delaunay variables, with the earth's spin rate σ taken as a small parameter of $O(1)$. The planet's potential will be considered up to the leading zonal and leading tesseral

harmonics, an outline of the perturbation technique is given which is based on the Lie-Deprit - Kamel transform.

The Hamiltonian is then normalized through three successive canonical transformations to eliminating succession of the short, intermediate, and long period terms. The procedure followed facilitates such including higher order terms and higher coefficients of the geopotential.

2. THE GEOPOTENTIAL

The earth's gravitational potential is usually expressed by "Vinti's potential":

$$V = -\frac{\mu}{r} \sum_{n=0}^{\infty} \sum_{m=0}^n \left(\frac{R}{r}\right)^n P_n^m(\sin \delta) (c_{nm} \cos m\lambda + s_{nm} \sin m\lambda) \quad (1)$$

Where R : the equatorial radius of the earth. $\mu = GM_e$ is the product of the gravitational constant and the mass of the earth, and known as the earth's gravitational parameter, (r, λ, δ) are the geocentric coordinates with λ being measured east of Greenwich, $P_n^m(\sin \delta)$ are the associated legendre polynomials, and c_{nm} and s_{nm} are harmonic coefficients. The terms with $m=0$ correspond to zonal harmonics, those with $0 < m < n$ correspond to tesseral harmonics, while $m=n$ correspond to sectorial harmonics, J_2 measures the equatorial bulge of the earth and C_{22}, S_{22} measure the elliptical shape of the earth's equator. The coefficients C_{21} and S_{21} are vanishing small and since the origin is taken at the center of mass, the coefficients C_{10}, C_{11} and S_{11} will be zero; also both the tesseral and sectorial harmonics will be simply referred to as tesseral harmonics. With the previous considerations, and writing the zonal and tesseral harmonics separately, eqn. (1) will be:

$$v = -\frac{\mu}{r} + \sum_{n=2}^{\infty} Z'_n + \sum_{n=2}^{\infty} \sum_{m=2}^n T'_{nm} \quad (2)$$

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$$\dot{k}_D = v = \frac{\partial H_D}{\partial K_D}, \dot{K}_D = -\frac{\partial H_D}{\partial k_D} \quad (19)$$

Since \hat{H} does not depend on K_D , it can be taken as constant of integration. So that:

$$H_D = vK_D + \hat{H} \quad (20)$$

The variable K_D may be identified by means of the second of equations (19).

- (ii). Performing a canonical transformation so that the new angular variables become:

$$l = l_D, g = g_D, h = h_D - \sigma t, k = k_D \quad (21)$$

Where σ is the angular speed of the earth. To find the new momenta and the new Hamiltonian, we have:

$$\left(L_D dl + G_D dg + H_D dh_D + K_D dk \right) - [Ldl + Gdg + H(dh_D - \sigma dt) + Kdt] + (H - H_D) dt = d\tau \quad (22)$$

Where $d\tau$ is the total differential of a function that we choose to be zero. Equating the coefficients of earth differential to zero yields:

$$L = L_D, G = G_D, H = H_D, K = K_D \quad (23)$$

$$\text{And } H = H_D - \sigma H \quad (24)$$

So in terms of this set of variables the equations of motion become:

$$\dot{z} = MH_z^T \text{ Where } z = \text{col}(l_D, \dots, K_D) \quad (25)$$

$$\text{and } H = \frac{-\mu^2}{2L^2} - \sigma H + \sum_n Z'_n + \sum_n \sum_m T'_{nm} \quad (26)$$

Considering σ as the small parameter of the problem, the orders of magnitude of the involved parameters are defined as:

$$\sigma \equiv o(1), J_2 \equiv o(2), C_{nm}, S_{nm} \equiv o(4) \quad (27)$$

The Hamiltonian can now be expressed as a power series of σ

$$H = \sum_{n=0}^4 \frac{\sigma^n}{n!} H_n \quad (28)$$

Where we retain the component of (28) up to 4th order in σ , i.e. up to J_2 in zonal harmonics and up to C_{22}, S_{22} in tesseral harmonics, so the components will be as follows:

$$H_0 = \frac{-\mu^2}{2L^2} \quad (29)$$

$$H_1 = -H \quad (30)$$

$$H_2 = \frac{A_2}{L^6} \varphi^3 z_2 \quad (31)$$

$$H_3 = 0 \quad (32)$$

$$H_4 = \frac{\varphi^3}{L^6} T_{22} \quad (33)$$

Where A_2 is a zero order constant, according to equations (26), (3) and (5) is given by:

$$A_2 = \frac{\mu^4 R^2 J_2}{2\sigma^2} \quad (34)$$

$$z_2 = (3S^2 - 2) - 3S^2 \cos F_{22} \quad (35)$$

$$\text{And } T_{21} = 0, C_{21}, S_{21} \rightarrow 0 \quad (36)$$

$$T_{22} = \gamma_{22} \left[S^2 + (2 - S^2) \cos F_{22} \right] + 2\Gamma_{22} C \sin F_{22} \quad (37)$$

$$\text{Where } \gamma_{22} = A_{22} \cos 2h + B_{22} \sin 2h \quad (38)$$

$$\Gamma_{22} = B_{22} \cos 2h - A_{22} \sin 2h \quad (39)$$

And the A_{22}, B_{22} are zero order constants given by:

$$A_{22} = \frac{-36\mu^4 R^2}{\sigma^4} c_{22} \quad (40)$$

$$B_{22} = \frac{-36\mu^4 R^2}{\sigma^4} s_{22} \quad (41)$$

4. THE PERTURBATION TECHNIQUE

We now outline the perturbation technique up to 4th order in the secular, 3rd order in the intermediate and 2nd order in the short periodic terms.

Let ε be the small parameter of the problem and let the considered system of differential equations to be:

$$\dot{u} = H_U^T, \dot{U} = -H_U^T \quad (42)$$

Where (u, U) is the six-vector of adopted canonical variables, the Hamiltonian is assumed expandable as:

$$H = H_0 + \sum \frac{\varepsilon^n}{n!} H_n \quad (43)$$

And the system with $H = H_0$ is assumed integrable with

$$H_0 = H_0(U_1)$$

What is required is to construct three canonical transformation (u, U; ε) \rightarrow (u', U'), (u', U'; ε) \rightarrow (u'', U'') and (u'', U''; ε) \rightarrow (u''', U''') analytic in ε at $\varepsilon = 0$ to eliminate in succession the short, intermediate and long period terms from the Hamiltonian such that U''' reduce to constants and u''' become linear functions of time, where the short period terms are those periodic in the mean anomaly, $u_1 = 1$, the

intermediate terms are those periodic in the longitude of the node, $u_2 = h$, and the long period terms are those periodic in the argument of perigee, $u_3 = g$. The transformed Hamiltonians and the corresponding generators will be assumed expandable as:

$$H^* (-, u'_2, u'_3; U'; \varepsilon) = H_0^* (U'_1) + \sum_{n=1} \frac{\varepsilon^n}{n!} H_n^* (-, u'_2, u'_3; U') \quad (44)$$

$$H^{**} (-, u''_3; U''; \varepsilon) = H_0^{**} (U''_1) + \sum_{n=1} \frac{\varepsilon^n}{n!} H_n^{**} (-, u''_3; U'') \quad (45)$$

$$H^{***} (-; U'''; \varepsilon) = H_0^{***} (U'''_1) + \sum_{n=1} \frac{\varepsilon^n}{n!} H_n^{***} (-; U''')$$

We will make use of the following equations during the process of elimination.

$$G_j = L_j - \sum_{m=0}^{j-2} \binom{j-1}{m} L_{m+1} G_{j-m-1} \quad (46)$$

$$H_0^* = H_0 \quad (47)$$

$$H_n^* = H_n + L_n H_0 + \sum_{j=1}^{n-1} \left[\binom{n-1}{j-1} L_j H_{n-j} + \binom{n-1}{j} G_j H_{n-j}^* \right], n \geq 1 \quad (48)$$

5. ELIMINATION OF SHORT PERIOD TERMS

The basic identities are:

$$H_0^* = H_0 \quad (49)$$

$$H_n^* = \tilde{H}_n + (H_0; w_n)$$

Let u'_1 be the fast variable in H , we choose H_n^* to be the average of \tilde{H}_n over u'_1 ; i.e.

$$H_n^* = \langle \tilde{H}_n \rangle_{u'_1} \quad (50)$$

$$P_n = \tilde{H}_n - H_n^* = (w_n; H_0)$$

$$\text{So that: } w_n = \left(\frac{\partial H_0}{\partial U'_1} \right)^{-1} \int P_n du'_1 \quad (51)$$

Where we apply the previous equations up to H_4^* , w_2 .

6. ELEMENTS OF THE SHORT PERIOD TRANSFORMATION AND ITS INVERSE

These are obtained from the equations for the vector transformation, namely:

$$u = u' + \sum_{n=1}^3 \frac{\varepsilon^n}{n!} u'^{(n)} \quad (52)$$

$$U = U' + \sum_{n=1}^3 \frac{\varepsilon^n}{n!} U'^{(n)}$$

Where

$$u'^{(n)} = \frac{\partial w_n}{\partial U'} + \sum_{j=1}^{n-1} \binom{n-1}{j} G_j u'^{(n-j)}, n \geq 1 \quad (53)$$

$$U'^{(n)} = -\frac{\partial w_n}{\partial u'} + \sum_{j=1}^{n-1} \binom{n-1}{j} G_j U'^{(n-j)}, n \geq 1$$

And for the inverse transformation:

$$u' = u + \sum_{n=1}^3 \frac{\varepsilon^n}{n!} u^{(n)}(u, U) \quad (54)$$

$$U' = U + \sum_{n=1}^3 \frac{\varepsilon^n}{n!} U^{(n)}(u, U)$$

Where

$$u^{(n)} = -u'^{(n)} + \sum_{j=1}^{n-1} \binom{n-1}{j} G_j u'^{(n-j)}, n \geq 1 \quad (55)$$

$$U^{(n)} = -U'^{(n)} + \sum_{j=1}^{n-1} \binom{n-1}{j} G_j U'^{(n-j)}$$

7. THE INTERMEDIATE TRANSFORMATION

The procedure is essentially similar to that at the short period transformation with the averages taken over u''_2 , so:

$$H_0^{**} = H_0^* \quad (56)$$

$$H_n^{**} = H_n^* + \sum_{j=1}^{n-1} \left\{ \binom{n-1}{j-1} (H_{n-j}^*; w_j^*) + \binom{n-1}{j} G_j^* H_{n-j}^{**} \right\} + (H_0^*; w_n^*)$$

Since H_n^{**} and H_n^* are independent of u''_2 , we may choose w_n^* also independent of u''_1 , then the last term vanishes and the last equation reduces to

$$H_n^{**} = H_n^* + \sum_{j=1}^{n-1} \left\{ \binom{n-1}{j-1} (H_{n-j}^*; w_j^*) + \binom{n-1}{j} G_j^* H_{n-j}^{**} \right\} \quad (57)$$

The equations involved may be outlined as before with the change $H \rightarrow H^*$, $H^* \rightarrow H^{**}$, $w \rightarrow w^*$, $u', U' \rightarrow u'', U''$

Order (1)

$$H_1^{**} = H_1^* + (H_0^*; w_1^*) = H_1^* \quad (58)$$

Where we note that $H_0^*(U_1^* = U_1'') = H_0^*(U'')$ and w^* is independent at u_1'' so $(H_0^*; w_1^*) = 0$

Order (2)

$$G_1 = L_1^* \\ H_2^{**} = H_2^* + (H_1^*; w_1^*) + (H_1^{**}; w_1^*) = H_2^* + 2(H_1^*; w_1^*) \quad (59)$$

We choose

$$H_2^{**} = \langle H_2^* \rangle_{u_2''} \\ P_2^* = H_2^* - H_2^{**} = 2(w_1^*; H_1^*) \quad (60)$$

Let

$$P_n^* = \sum_{i,j} c_n^{ij} \cos(iu_2'' + ju_3'' + \alpha_n^{ij}) \quad (61)$$

Where c_n are functions of U_1'' and α_n^{ij} are numerical constants to account for the phase then

$$w_1^* = \frac{1}{2} \sum_{i,j} \frac{c_2^{ij} \sin(iu_2'' + ju_3'' + \alpha_2^{ij})}{i \frac{\partial H_1^*}{\partial u_2''} + j \frac{\partial H_1^*}{\partial u_3''}} \quad (62)$$

Similarly we find order (3), elements of the intermediate transformation are obtained by the same equations used for the short period transformation and the use of the interchanges used previously. The long period transformation and its elements are found in a similar manner.

8. NORMALIZATION

Equation (28) shows that the Hamiltonian of the problem is degenerate with l is the fast variable, h is intermediate variable, and g is slow one.

So the Hamiltonian (28) is normalized through three successive canonical transformations.

8.1. The Short Period Terms

Averaging over l and following the steps outlined in the procedure for the short period transformation we obtain

$$H_0^* = -\frac{\mu^2}{2L^2}$$

$$H_1^* = -H'$$

$$H_2^* = \frac{A_2}{L'^6} \langle \phi^3 z_2 \rangle_{l'} = A_2 \frac{\eta'^3}{L'^6} (3S'^2 - 2)$$

$$H_3^* = 0$$

$$H_4^* = \tilde{T}'_{22} + \frac{9A_2^2}{\mu^2} \sum_{i=0}^2 (\theta_i^c \cos 2ig + \theta_i^s \sin 2ig)$$

$$w_1 = 0$$

$$w_2 = \frac{A_2}{\mu^2 G'^3} \left\{ (3S'^2 - 2)(f' - l' + e' \sin f') - \frac{3}{2} S'^2 \left[\frac{e}{3} \sin F_{32} + \sin F_{22} + e \sin F_{12} \right] \right\}$$

8.2. Averaging over h'' and Following the Procedure Illustrated we Get

$$H_0^{**} = H_0^* = -\frac{\mu^2}{2L'^2}$$

$$H_1^{**} = H_1^* = -H''$$

$$H_2^{**} = H_2^* = A_2 \eta''_{33} \theta''_{33}$$

$$H_3^{**} = 0$$

$$H_4^{**} = \frac{9A_2^2}{\mu^2} \sum_{i=0}^2 (\theta_i^{c''} \cos 2ig'' + \theta_i^{s''} \sin 2ig'')$$

$$w_1^* = 0$$

$$w_2^* = 0$$

8.3. Long Period Transformation

Averaging over g''' and following the procedure we get

$$H_0^{***} = -\frac{\mu^2}{2L''^2}$$

$$H_1^{***} = -H'''$$

$$H_2^{***} = A_2 \eta'''_{33} \theta'''_{33}$$

$$H_3^{***} = 0$$

$$H_4^{***} = \frac{9A_2^2}{\mu^2} \theta_0^{c''}$$

$$w_1^{**} = 0$$

$$w_2^{**} = \frac{1}{6I_c'''} \left[\frac{9A_2^2}{2\mu^2} \sum_{i=1}^2 \frac{1}{i} (\theta_i^{c''} \sin 2ig'' - \theta_i^{s''} \cos 2ig'') \right]$$

CONCLUSION

The present work aims at formulating the problem of the motion of an artificial satellite around a slowly rotating planet, this problem has many applications particularly for missions launched to study the potential harmonics of the earth (or any other planet), and for communication satellites. The formulation is developed in a simple canonical form expressed in terms of a set of Delaunay elements modified to allow for the appearance of the independent variable in the Hamiltonian, this enables using very powerful tools for solv-

ing for the motion using canonical perturbation approaches such as the methods of von Ziepel's and those based on a Lie series and transform. It is important to stress the importance of such formulation due to the slow rotation of the moon). Though the solution would require some modification due to the varying nature of the lunar potential. In similar works J_2 is usually used as the small parameter which provides no simple means to account for the rotation speed either slow or fast. In the present work the rotation speed σ is used as the small parameter, thus enabling to account for its order.

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CONFLICTS OF INTEREST

None declared.

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