3D Modeling of Wave-Seabed-Pipeline in Marine Environments

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Abstract: In this study, a three-dimensional numerical model is developed, based on the Finite Element Method, to analyse the behaviour of soil under the wave loading. The pipeline is assumed to be rigid and anchored within a trench. The influence of wave obliquity on seabed responses, the pore pressure and soil stresses, are studied, which cannot be handled by the existing 2D models. It is revealed that three-dimensional characteristics systematically affect the distribution of soil response around the circumference of the underwater pipeline. Based on new 3D model, the effects of wave and soil characteristics and trench configuration on the wave-induced seabed instability are discussed in detail.

INTRODUCTION

Offshore pipelines are typically constructed as either underwater-laid or submarine-buried structures. From the design-engineering point of view, these two categories of marine pipelines are characterized by their different instability mechanisms and thus design procedures. Underwater-laid pipelines are mainly constructed in deep waters and laid on the seabed surface. In this category, the pipeline is subject to the instability due to the influence of presence of structure on its surrounding flow pattern, scouring near the pipeline, formation of free spans and the soil failure at span shoulders. This subject has been investigated by various researchers. Recently, the theory and literature of scouring around marine pipelines are outlined by Sumer and Fredsoe [1]. At the same time, underwater-laid pipelines are also found vulnerable to the liquefaction of underlying seabed soil layers. This issue, also, recently has attracted attention from researchers and pipeline engineers. Sumer et al. [2] and Teh [3] are the two recent contributions to the problem of the on-bottom stability of marine pipelines on liquefied seabeds.

In shallow water, submarine pipelines are often buried within the seabed for the protection against human activities such as ship anchoring, dredging and fishing. In this region, ocean waves propagating over the seabed exert a significant dynamic pressure on the seabed soil. The porous seabed, therefore, undergoes consolidation under the wave loading. Considerable amounts of wave-associated pore pressure and stresses are consequently generated within the soil matrix. Such excessive pore pressure and the accompanied loss of soil effective stress will expose the seabed to the high potential of liquefaction. At the same time, large wave-associated soil shear stresses will further impose the risk of seabed shear failure. The liquefied seabed near the pipeline provides the ground for the structure to sink or float within the bed due to its self-weight, while the shear failure instigates large horizontal movements of pipeline. It is also possible for the pipeline in a mobilized seabed to displace under strong bottom currents. Regardless of its pattern, a large pipeline deformation is accompanied by considerable internal stresses within the structure; and thus may result in its failure. Therefore, it is crucial to gain a realistic understanding to wave-associated seabed behaviour near submarine buried pipelines, in order to enhance the safety of pipeline, reduce the risk of disruption in energy flow and prevent the economical and environmental hazards of pipe failure.

Two well-known main mechanisms of soil instabilities are liquefaction and shear failure. The former is the loss of soil’s ability to withstand any normal or shear stress, while behaves as fluid [4]. The latter, is the soil loosing the ability to resist further shear stresses and thus, soil layers sliding on each other. To predict either phenomenon, wave-induced seabed responses, i.e. pore pressure, effective and normal stresses, should be evaluated and used in conjunction with appropriate soil instability criteria.

Numerous studies have concentrated on the evaluation of seabed responses under wave loading [5-7]. However, the majority of them considered a two-dimensional wave-soil-pipeline interaction problem. These studies only deal with cases, in which the wave approaches normal to the orientation of pipeline. However, in the real ocean environment, waves may approach the pipeline from any direction. Therefore, it is necessary to establish a three-dimensional model to study these circumstances and gain a realistic understanding of soil behaviour under an oblique wave loading. The primary aim of this research is therefore to answer the question of “how significant are the three-dimensional effects on the wave-induced responses of seabed soil near a submarine buried pipeline?”

Among available investigations, only two studies have addressed this problem from a three-dimensional point of view. The first study was the BIEM model of Lennon [8, 9], in which potential theory was applied to obtain the wave-induced pore pressure in the presence of a pipeline, while waves were considered to approach from multiple directions.
In fact, the potential theory is considered as being outdated, since it does not provide a realistic prediction of wave-induced seabed behaviour. Secondly, even if the potential theory could be considered as applicable in a very limited range of soils, it does not provide any information on soil stresses. In other words, it is incapable of evaluating the potential of soil instability near the pipeline.

In another study, Chen et al. [10] addressed a similar problem by using the consolidation equations of Biot [11]. Although Biot theory is accepted as suitable for describing the seabed behaviour under loading, Chen et al. [10] questionably concluded that there is no difference between two-dimensional and three-dimensional cases. This conclusion is found to be incorrect in the present study. It is possible that such a conclusion is drawn based on the fact that Chen et al. [10] only examined one set of wave/soil/pipe properties in their research. Meanwhile, similar to Lennon [9], they also did not investigate soil stresses. The present study, however, reveals that the three-dimensional effects are significant particularly for soil normal and effective stresses. Therefore, the current research is intended to study both wave-induced pore pressure and stresses for a wide range of soil/pipe/wave properties, using a 3-D model.

A rare number of two-dimensional studies such as Jeng and Cheng [12] investigated the potential of wave-induced seabed shear failure in the presence of a buried pipeline. However, to the author’s knowledge, even among two-dimensional investigations, there is no study to systematically investigate both shear failure and liquefaction near submarine pipelines and over a wide range of wave/soil/pipe properties. At the same time, no three-dimensional model is also available in the literature to address three-dimensional effects on the potential of wave-induced shear failure and liquefaction around buried pipelines. Therefore, seabed instabilities will also be systematically investigated in the present study.

3D BOUNDARY VALUE PROBLEM

A submarine pipeline is considered to be buried within a trench as shown in the cross-sectional view in Fig. (1). As illustrated, the x-direction is perpendicular to the trench lateral walls; the y direction is parallel to the pipeline; and the z axis is assumed to be positive upward from the mud-line and located at the mid trench width. On the other hand, the plane view of the problem configuration is also plotted in Fig. (2). Ocean waves are assumed to propagate in the positive X-direction. Therefore an incident wave angle of α is formed between the direction of wave progression (X-axis) and the pipe centreline (y-axis). For waves travelling parallel with the pipeline, thus, α=0°, while for waves propagating normal to the pipeline, hence, α=90°.

Governing Equations

The seabed soil surrounding a submarine buried pipeline consolidates under the dynamic pressure from ocean waves. Full three-dimensional Biot consolidation theory [11] is applied in this study to evaluate the seabed response associated with the action of waves. The application of this theory is based upon the following assumptions of the seabed behaviour:

- The Darcy law dominates the pore fluid flow through seabed voids.
- The soil skeleton is a linear elastic material and its behaviour follows the Hooke’s law.
- Both the pore fluid and soil skeleton are compressible materials.
- Unsteady velocities, i.e. accelerations, in both pore fluid flow and soil skeleton displacements are assumed to be small and therefore negligible.
- The pore fluid is a uniform material consisting of pore water and air bubbles; and its properties such as the air content and the compressibility do not change during and as the result of the consolidation process.
• The seabed soil is hydraulically and structurally isotropic.

• The seabed material is uniform and homogenous.

Fig. (3) shows a small cubic element of consolidating seabed soil with shear and normal total stresses acting on it. The element is considered large enough compared with the size of pores so that it may be treated as homogenous, and at the same time small enough so it may be mathematically considered infinitesimal.

![Fig. (3). Definition sketch: total stresses acting on a soil element.](image)

The equilibrium state of stress, in the $x$, $y$- and $z$- directions respectively, requires:

$$\frac{\partial \sigma_x}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + \frac{\partial \tau_{xz}}{\partial z} = 0$$  \hspace{1cm} (1)

$$\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_y}{\partial y} + \frac{\partial \tau_{yz}}{\partial z} = 0$$  \hspace{1cm} (2)

$$\frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \sigma_z}{\partial z} = 0$$  \hspace{1cm} (3)

in which, $\tau_j$ is the soil shear stress acting in the $j$- direction and in the plane normal to the $i$- direction; $\sigma_i$ represents total normal stress in the $i$- direction. On the other hand, the seabed material is reported to be highly saturated with the degree of saturation ranging from about 0.90 to 1.00 as pointed out in Esrig and Kirby [13]. In such nearly saturated condition, the relation between total and effective normal stresses of soil can be expressed, in any direction such as $i$-, as:

$$\sigma_i' = \sigma_i - p$$  \hspace{1cm} (4)

where, $\sigma_i'$ is the normal effective stress in $i$- direction. It is important to note that the relation (4) should be modified in partially saturated soils.

Substituting equation (4) into equations (1)-(3), gives:

$$\frac{\partial \sigma'_x}{\partial x} + \frac{\partial \tau'_{xy}}{\partial y} + \frac{\partial \tau'_{xz}}{\partial z} = \frac{\partial p}{\partial x}$$  \hspace{1cm} (5)

It is assumed that the soil skeleton is a linear elastic material. Therefore, stresses and strains in solid skeleton are related on the basis of Hooke’s law. That is:

$$\tau_{xy} = \tau_{yx} = G \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)$$  \hspace{1cm} (8)

$$\tau_{xz} = \tau_{zx} = G \left( \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right)$$  \hspace{1cm} (9)

$$\tau_{yz} = \tau_{zy} = G \left( \frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right)$$  \hspace{1cm} (10)

$$\sigma_x' = 2G \left( \frac{\partial u}{\partial x} + \frac{\mu}{1-2\mu} \varepsilon \right)$$  \hspace{1cm} (11)

$$\sigma_y' = 2G \left( \frac{\partial v}{\partial y} + \frac{\mu}{1-2\mu} \varepsilon \right)$$  \hspace{1cm} (12)

$$\sigma_z' = 2G \left( \frac{\partial w}{\partial z} + \frac{\mu}{1-2\mu} \varepsilon \right)$$  \hspace{1cm} (13)

in which, $G$ is the shear modulus of soil; $\mu$ is the Poisson’s ratio; $u, v$ and $w$ are soil displacements in $x$, $y$ and $z$- directions, respectively; and $\varepsilon$ is the volumetric soil strain defined as:

$$\varepsilon = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}$$  \hspace{1cm} (14)

Soil stresses, in relations (8) to (13), can be substituted into the equilibrium equations (5) to (7). This provides a system of partial differential equations for soil equilibrium in terms of soil displacements and the pore pressure:

$$G \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) + \frac{G}{1-2\mu} \frac{\partial \varepsilon}{\partial x} = \frac{\partial p}{\partial x}$$  \hspace{1cm} (15)

$$G \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) + \frac{G}{1-2\mu} \frac{\partial \varepsilon}{\partial y} = \frac{\partial p}{\partial y}$$  \hspace{1cm} (16)

$$G \left( \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} \right) + \frac{G}{1-2\mu} \frac{\partial \varepsilon}{\partial z} = \frac{\partial p}{\partial z}$$  \hspace{1cm} (17)

Finally, based on conservation of mass, the storage equation is used to describe the pore fluid flow:

$$k \nabla^2 p - \gamma_w \frac{\partial p}{\partial t} = \gamma_w \frac{\partial \varepsilon}{\partial t}$$  \hspace{1cm} (18)

The system of equilibrium equations for the soil matrix in (15)-(17) and the storage equation in (18) is known as the quasi-static soil consolidation theory as well as the Biot con-
solidation equations. They are sufficient to analyse the seabed behaviour under the wave loading. However, appropriate boundary conditions should be introduced in conjunction with these equations in order to solve the problem of wave-seabed-pipeline interaction.

In (18), the compressibility of pore fluid deviates from that of pure water based on the degree of saturation. In highly saturated soils \((S > 0.85)\), this is as:

\[
\beta = \frac{1}{K_w} + \frac{1 - S}{P_{w_0}}
\]

(19)

where, \(K_w\) \((\approx 2\, \text{GPa})\) is the true bulk modulus of elasticity of water; \(1/ K_w\) thus represents the compressibility of pure (fully saturated) water; and \(P_{w_0}\) is the absolute water pressure.

**Boundary Conditions**

Five sets of boundary conditions are required to solve the boundary value problem of wave-induced seabed responses in the presence of a pipeline. They are (i) Mudline Boundary Conditions (MBC), (ii) trench Bottom Boundary Conditions (BBC), (iii) Pipeline surface Boundary Conditions (PBC), (iv) Lateral Boundary Conditions in the \(x\)-direction (LBC\(_x\)), and (v) Lateral Boundary Conditions in the \(y\)-direction (LBC\(_y\)).

(i) **Mudline Boundary Condition (MBC)**

At the interface between the water body and the porous seabed, a wave dynamic pressure is introduced to the soil. The continuity of pressure between the two media, i.e. soil and water body, therefore requires that the pore pressure within the seabed to be identical to the wave pressure. That is:

\[
p = p_{bed}
\]

(20)

in which, \(p_{bed}\) represents the spatial and temporal variations of wave pressure at the seabed surface \((z=0)\). It will be shown in the next section that, based on the linear wave theory, the wave pressure at the mudline is:

\[
p_{bed} = \frac{\rho_w g H}{2 \cos k h} \cos(kX - \omega t)
\]

(21)

where, \(\rho_w\) is the sea water density; \(H\) is the wave height; \(h\) is water depth; and \(k\) and \(\omega\) are the wave number and frequency, respectively. Since the consolidation equations as presented in the previous section are proposed in the \(xyz\) coordinate system, the wave pressure in the relation (21) should be transformed to this system. For this purpose, the positive \(X\)-axis should be rotated \((90-\alpha)\)° clockwise about the \(z\)-axis to coincide with the positive \(x\)-axis. The rotational transformation matrix is:

\[
\begin{bmatrix}
X \\
y \\
z
\end{bmatrix} =
\begin{bmatrix}
\sin(\alpha) & \cos(\alpha) & 0 \\
-\cos(\alpha) & \sin(\alpha) & 0 \\
0 & 0 & 1
\end{bmatrix}
\begin{bmatrix}
x \\
y \\
z
\end{bmatrix}
\]

(22)

Substituting \(X\) from (22) into (21), the mudline wave pressure will be:

\[
p = p_{bed} = \frac{\rho_w g H}{2 \cos k h} \cos(k_x x + k_y y - \omega t)
\]

(23)

in which, \(k_x\) and \(k_y\) are projections of wave number:

\[
k_x = k \sin \alpha \quad \text{and} \quad k_y = k \cos \alpha
\]

(24)

As previously stated total normal soil stresses in fact consist of effective normal stresses acting on soil skeleton and the pore pressure. On the seabed surface, the total vertical stress \(\sigma_z\) is generated by and identical to the wave pressure at the mudline. At the same time, at this point, the wave pressure is also identical to the pore pressure within the seabed due to the continuity of pressure between wave and seabed mediums. Therefore, the vertical effective stress \(\sigma'_{z}\) becomes zero at the seabed surface. In other words, the portion of vertical stresses carried by the soil skeleton vanishes at the water-soil interface, i.e.:

\[
\sigma'_{z} |_{z=0} = 2G \left( \frac{\partial w}{\partial z} + \frac{1}{1-2\mu} \frac{\partial v}{\partial y} \right) |_{z=0} = 0
\]

(25)

Finally, there are two other requirements to be met on the seabed surface. They are that the shear stresses acting on seabed surface should be prescribed. These stresses are in fact generated by the action of viscous flow in the boundary layer adjacent to the mudline. The effect of shear stresses is well known as responsible for the sediment transport in a thin layer of porous seabed. However, considering the seabed domain as a whole, mudline shear stresses are found to have negligible contributions towards the consolidation process of a seabed soil, as examined by [14-16]. Therefore,

\[
\tau_{xz} |_{z=0} = G \left( \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right) |_{z=0} = 0
\]

(26)

\[
\tau_{yz} |_{z=0} = G \left( \frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right) |_{z=0} = 0
\]

(27)

Equations (23), (25)-(27) form the mudline boundary conditions.

(ii) **Boundary Conditions on Impermeable Fixed Rough Surfaces (BBC, PBC, LBCx)**

In this study, it is assumed that the surfaces of the trench walls, trench bottom and pipeline are impermeable. Such an assumption requires that pore fluid flow cannot penetrate into these surfaces. Therefore, the gradient of pore pressure normal to these surfaces should be zero. That is:

\[
\frac{\partial p}{\partial r} = 0 \quad \text{on,}
\]

\[
\begin{align*}
\text{trench walls:} & \quad x = \pm \frac{w}{2} \\
\text{trench bottom:} & \quad z = -d \\
\text{pipe surface:} & \quad x^2 + z^2 = \frac{D^2}{4}
\end{align*}
\]

(28)

in which, \(r\) is the direction normal to the boundary surface, specified as \(r = x\) on the trench lateral walls; \(r = z\) on the trench bottom. Also, \(w\) and \(d\) are the trench width and depth, respectively; and \(D\) is the pipe outer diameter. On the other hand, it is assumed that these surfaces are fixed, rigid and rough. Therefore, a no-slip condition between soil and boundary surfaces requires:
Assumptions, which are made on the boundary conditions at the pipe-soil interface, influence seabed responses. Among available studies, Cheng and Liu [17] considered the case of an unanchored pipeline, Jeng et al. [18] examined pipe internal stresses and deformations, and recently, Luan et al. [19] studied the contact problem between the soil and the pipeline, where slipping was also allowed at the interface. In the present study, however, the concentration is on three-dimensional aspects of wave-seabed-pipeline interaction problem. Therefore, a simplified boundary condition, as in relation (29), is applied on pipe-soil interface. Besides, these conditions can also be justified as reasonable in cases such as anchored pipelines with a concrete coating.

(iii) Lateral Boundary Conditions in y- Direction (LBCy)

An examination of Fig. (2) reveals that a periodic-type lateral boundary condition is required in the y- direction. Before proceeding to this issue, however, it is necessary to introduce conditions upon which the response of the seabed soil at two locations can be considered as being identical to each other. In fact, the soil elements at any two points respond identically to the wave loading, only if these two points are:

(a) located at the same depth (z) beneath the mudline (zi=zi).

(b) located at the same position (x) measured from the pipe centreline (xi=xj).

(c) exposed to similar wave loadings on the seabed surface above them (wave phase1= wave phase2+2mπ).

where, m is an integer. As shown in Fig. (2), these conditions are satisfied among sections A-A and A'-A', on which the wave loadings are 2π distant from each other. Therefore, a periodic boundary condition in the y- direction can be proposed between any two such sections, provided that they are Δy = L/ cos α distant from each other. This issue can also be mathematically confirmed by an inspection of equations (23) and (24).

Seabed Response_a b c = Seabed Response_a b c d (30)

That is,

\[ u(x, y, z) = u(x, y + \frac{L}{\cos \alpha}, z) \] (31)

\[ v(x, y, z) = v(x, y + \frac{L}{\cos \alpha}, z) \] (32)

\[ w(x, y, z) = w(x, y + \frac{L}{\cos \alpha}, z) \] (33)

\[ p(x, y, z) = p(x, y + \frac{L}{\cos \alpha}, z) \] (34)

It is worthy to note that for the special case of waves that are propagating normal to the pipeline (α=90°), the periodic lateral boundary condition in the y- direction can be applied between any two sections with an arbitrary distance Δy. Nonetheless, for numerical simulation purposes, a minimum length of computational domain in the y- direction is considered. This will be discussed in the next section.

3D FINITE ELEMENT MODEL

The three-dimensional boundary value problem, presented in the previous section, will be solved numerically. For this purpose, the Finite Element Method is adopted to develop a numerical model. The proposed model, WSPI-3D (Wave-Soil-Pipe Interaction simulator in 3-D), is constructed with the aid of the PDE module of Comsol Multiphysics, a Finite Element Analysis software. The flexibility of Comsol Multiphysics, as it works in conjunction with MATLAB, further allows the implementation of a well-organized post-processing module within WSPI-3D. For more details on Comsol Multiphysics, the reader is referred to [20].

In this section, general characteristics of the developed FE model, as well as details of spatial and temporal discretization in the FE system will be presented. Furthermore, the new 3-D numerical model will be rigorously examined and validated against an available analytical solution, experimental data, as well as, a previous two-dimensional numerical model.

Finite Element Formulations

In the present model, Quadratic (2nd order) Lagrange elements have been used to ensure the second order of accuracy in evaluating seabed responses. The three-dimensional finite elements are considered to be Hexahedral. Details of the FE mesh pattern are also presented in this section. Meanwhile, numerical integrations are approximated by using the Quadrature formula, which computes the integral over a mesh element by taking a weighted sum of the integrand - evaluated in a finite number of points in the mesh element. The order of Quadrature formula, as a rule of thumb, is taken to be twice the order of the adopted finite element. Thus, the 4th order Quadrature formula is used. The time-dependant consolidation problem is solved by using the GMRES linear system solver along with an Incomplete LU preconditioner scheme. The problem is solved to obtain the pore pressure and soil displacement fields. These were then used to extract soil stresses by using equations (8) to (13). Post-processing subroutines are then applied to transfer the stress tensors into the desired coordinate system, as well as, to extract amplitudes and phase lags of seabed responses.

Spatial Discretization: Finite Element Mesh

The occurrence of soil instability in the vicinity of a pipeline leads to the instability of the structure itself and therefore to its failure. Consequently, it is the interest of this study to evaluate seabed responses near to and in particular around the pipeline. On the other hand, the presence of a structure such as a pipeline is expected to trigger a stress concentration in the region close to the structure. Therefore, it is necessary to refine the Finite Element Mesh near the pipeline. The cylindrical geometry of the structure also suggests that a far-field mesh has to be modified in conformity to this ge-
ometry, when it gets closer to the structure. In the region near the pipeline, hence, a specific mesh pattern is considered herein as illustrated in Fig. (4). Some preliminary numerical results also suggest that it is sufficient for such a specific pattern to spread to twice the pipe diameter, as is shown. In fact, this is because of the concentration of stress, due to the presence of the structure, being likely to vanish beyond this distance. On the other hand, the adopted pattern allows the mesh to refine as it moves towards the structure.

Numerical experiments were carried out in this study to determine the minimum required mesh resolution near the pipeline that provides a desired accuracy for the evaluation of wave-induced seabed responses. In the present study, such a desired accuracy is defined as when numerical results contain less than 1% of error in comparison with the exact solution. However, no exact solution is yet available for the response of seabed soil in the presence of a pipeline. In this regard, it is possible to consider a benchmark numerical solution to act as the exact solution. For this purpose, benchmark numerical results should be obtained based on using an extremely fine mesh.

The refinement of the introduced mesh pattern can be controlled by a set of three parameters. They are: $n_p$ showing the number of mesh divisions around the pipeline perimeter; $n_R$ representing the number of mesh divisions in the radial direction on the pipe cross-section; $n_l$ standing for the number of mesh divisions over one wave length along the pipe centreline, which coincides to the y- direction in Fig. (4). Now, let us assume that the numerical results would fall on the exact solution, when an extremely fine mesh, which is generated by adopting $n_p = 64$, $n_R = 12$ and $n_l = 40$, is used. This mesh refinement, therefore, corresponds to the benchmark numerical solution. It is worthy to note that this assumption will be automatically confirmed upon the convergence of coarse-mesh numerical results to the benchmark solution. It is also assumed that the benchmark solution may be achieved when FE Analysis is continued for up to five wave periods (that is $n_c = 5$) to ensure a fully stable numerical scheme. The benchmark FE time step ($\Delta t$) is also considered as small as $1/90$ of the wave period.

Fig. (4). Definition Sketch: 3-D Finite Element Mesh in the vicinity of pipeline.

Table 1. Properties of Wave, Soil and Pipe Used in Numerical Tests to Determine Required Mesh Refinement

<table>
<thead>
<tr>
<th>Wave Properties</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Water depth ($h$)</td>
<td>10 m</td>
</tr>
<tr>
<td>Wave period ($T$)</td>
<td>10 sec</td>
</tr>
<tr>
<td>Wave height ($H$)</td>
<td>2 m</td>
</tr>
<tr>
<td>Wavelength ($L$)</td>
<td>92.32 m</td>
</tr>
<tr>
<td>Incident wave angle ($\alpha$)</td>
<td>0 or 90 degree</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Soil properties</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Shear stiffness ($G$)</td>
<td>5 MPa</td>
</tr>
<tr>
<td>Poisson’s ratio ($\mu$)</td>
<td>0.33</td>
</tr>
<tr>
<td>Porosity ($n$)</td>
<td>0.40</td>
</tr>
<tr>
<td>Saturation ($S$)</td>
<td>98.5%</td>
</tr>
<tr>
<td>Permeability ($k$)</td>
<td>$10^{-1}$ m/sec</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Trench/pipeline properties</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Trench width ($w$)</td>
<td>4 m</td>
</tr>
<tr>
<td>Trench depth ($d$)</td>
<td>4 m</td>
</tr>
<tr>
<td>Pipe diameter ($D$)</td>
<td>2 m</td>
</tr>
<tr>
<td>Pipe burial depth ($B$)</td>
<td>2 m</td>
</tr>
</tbody>
</table>

Hereafter, results from a set of numerical tests will be presented. Tests are aimed at identifying the minimum mesh refinement that permits soil responses to fall within 1% of deviation from the defined benchmark solution. Properties of wave, soil and pipeline, which are used in numerical tests, are listed in Table (1) unless otherwise stated. In this section, $\Delta t = T/36$ and $n_c = 2$ are adopted to perform the FE analysis.

It is essential for FEM modelling to examine the influence of mesh resolution on both the pore pressure and soil stresses around the pipeline. For this purpose and as a measure of seabed responses around the structure, integrals of pore pressure and soil stresses over the perimeter of pipe cross-section will be studied. These are as $\int_s \frac{p}{p_w} ds$, $\int_s \frac{\sigma'}{p_w} ds$, $\int_s \frac{\sigma^'}{p_w} ds$, and $\int_s \frac{\sigma^'}{p_w} ds$, in which $s$ indicates the circumference of pipe cross-section. In fact, it was also possible to individually study the effect of mesh resolution on a number of points around the structure. However, using the integrated form provides a general view of accuracy of the model in evaluating the seabed behaviour around the pipeline as a whole. The wave dynamic pressure on seabed surface oscillates periodically over a wave period and therefore does the integral of a seabed response. But, the amplitude of this oscillation is used herein to justify the required mesh refinement.

It is convenient to consider the case of ocean waves propagating normal to the pipeline ($\alpha=90^\circ$) to investigate the effect of mesh refinements in the $xz$ plane, i.e. $n_p$ and $n_R$. The boundary value problem will be reduced to a two-dimensional soil consolidation problem under these circum-

1 It will be shown in the next section that $\Delta t = T/36$ and $n_c = 2$ correspond to an error of no more than one percent in numerical results and thus are sufficient for the present study.
stances. Results of numerical simulations, presented in Tables (2) and (3), suggest that by the use of \( n_p = 32 \) and \( n_R = 8 \) the deviation of integrated soil responses from the benchmark solution will be suppressed into less than 1%. Therefore, it is sufficient to consider a finite element mesh, which divides the pipeline circumference into 32 sections, while it splits the radial direction into 8 segments. It is worthy to mention that some investigations such as Magda [21] also used a simplified two-dimensional version of mesh pattern that is depicted in Fig. (4). However, Magda [21] only examined the influence of mesh resolution on wave-induced uplift forces acting on the pipeline. The uplift force is in fact a measure of pore pressure around the circumference of structure, as a whole. Nevertheless, the present tabulated numerical results reveal that soil stresses would suffer from much more significant errors, if a coarse mesh is inappropriately used. Thus, the effect of mesh resolution on soil stresses also has to be investigated.

To study the mesh refinement along the pipeline, i.e. \( n_L \), an ocean wave propagating parallel with the pipe orientation (\( \alpha = 0^\circ \)) is considered. This is because under these circumstances, the wave loading varies along the pipeline. Therefore, the number of mesh divisions along the structure is expected to influence the accuracy of numerical simulations. Table (4) clearly indicates that a refinement of \( n_L = 20 \) per wave length is sufficient, for this dimension. It is, however, worthy to note that although \( n_L = 20 \) keeps the deviation

### Table 2. Seabed Responses Around Pipeline for Various Mesh Refinements \( (n_p) \) while \( \alpha = 90^\circ \); \( n_R = 12 \); \( n_L = n_p/a \)

<table>
<thead>
<tr>
<th>( n_p )</th>
<th>( \int_S \frac{P}{p_o} , ds )</th>
<th>Deviation from Benchmark Solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>8</td>
<td>3.641</td>
<td>2.65%</td>
</tr>
<tr>
<td>16</td>
<td>3.703</td>
<td>0.99%</td>
</tr>
<tr>
<td>32</td>
<td>3.740</td>
<td>0.00%</td>
</tr>
<tr>
<td>64</td>
<td>3.736</td>
<td>0.11%</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>( n_p )</th>
<th>( \int_S \frac{\sigma_i}{p_o} , ds )</th>
<th>Deviation from Benchmark solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>8</td>
<td>0.096</td>
<td>49.47%</td>
</tr>
<tr>
<td>16</td>
<td>0.192</td>
<td>1.05%</td>
</tr>
<tr>
<td>32</td>
<td>0.190</td>
<td>0.00%</td>
</tr>
<tr>
<td>64</td>
<td>0.190</td>
<td>0.00%</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>( n_p )</th>
<th>( \int_S \frac{\sigma_{ij}}{p_o} , ds )</th>
<th>Deviation from Benchmark solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>8</td>
<td>0.161</td>
<td>78.53%</td>
</tr>
<tr>
<td>16</td>
<td>0.774</td>
<td>3.20%</td>
</tr>
<tr>
<td>32</td>
<td>0.750</td>
<td>0.00%</td>
</tr>
<tr>
<td>64</td>
<td>0.748</td>
<td>0.27%</td>
</tr>
</tbody>
</table>

### Table 3. Seabed Responses Around Pipeline for Various Mesh Refinements \( (n_R) \) while \( \alpha = 90^\circ \); \( n_p = 32 \); \( n_L = n_p/a \)

<table>
<thead>
<tr>
<th>( n_R )</th>
<th>( \int_S \frac{P}{p_o} , ds )</th>
<th>Deviation from Benchmark Solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>3.729</td>
<td>0.29%</td>
</tr>
<tr>
<td>6</td>
<td>3.737</td>
<td>0.08%</td>
</tr>
<tr>
<td>8</td>
<td>3.744</td>
<td>0.11%</td>
</tr>
<tr>
<td>10</td>
<td>3.711</td>
<td>0.78%</td>
</tr>
<tr>
<td>12</td>
<td>3.740</td>
<td>0.00%</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>( n_R )</th>
<th>( \int_S \frac{\sigma_i}{p_o} , ds )</th>
<th>Deviation from Benchmark solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>0.198</td>
<td>4.22%</td>
</tr>
<tr>
<td>6</td>
<td>0.193</td>
<td>1.58%</td>
</tr>
<tr>
<td>8</td>
<td>0.192</td>
<td>1.05%</td>
</tr>
<tr>
<td>10</td>
<td>0.190</td>
<td>0.00%</td>
</tr>
<tr>
<td>12</td>
<td>0.190</td>
<td>0.00%</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>( n_R )</th>
<th>( \int_S \frac{\sigma_{ij}}{p_o} , ds )</th>
<th>Deviation from Benchmark solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>0.743</td>
<td>0.93%</td>
</tr>
<tr>
<td>6</td>
<td>0.747</td>
<td>0.40%</td>
</tr>
<tr>
<td>8</td>
<td>0.751</td>
<td>0.13%</td>
</tr>
<tr>
<td>10</td>
<td>0.750</td>
<td>0.00%</td>
</tr>
<tr>
<td>12</td>
<td>0.750</td>
<td>0.00%</td>
</tr>
</tbody>
</table>

### Table 4. Seabed Responses Around Pipeline for Various Mesh Refinements \( (n_L) \) while \( \alpha = 0^\circ \); \( n_p = 32 \); \( n_R = 8 \)

<table>
<thead>
<tr>
<th>( n_L )</th>
<th>( \int_S \frac{P}{p_o} , ds )</th>
<th>Deviation from Benchmark solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>3.721</td>
<td>0.32%</td>
</tr>
<tr>
<td>20</td>
<td>3.707</td>
<td>0.05%</td>
</tr>
<tr>
<td>40</td>
<td>3.709</td>
<td>0.00%</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>( n_L )</th>
<th>( \int_S \frac{\sigma_i}{p_o} , ds )</th>
<th>Deviation from Benchmark solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>0.191</td>
<td>1.60%</td>
</tr>
<tr>
<td>20</td>
<td>0.187</td>
<td>0.53%</td>
</tr>
<tr>
<td>40</td>
<td>0.188</td>
<td>0.00%</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>( n_L )</th>
<th>( \int_S \frac{\sigma_{ij}}{p_o} , ds )</th>
<th>Deviation from Benchmark solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>0.309</td>
<td>1.32%</td>
</tr>
<tr>
<td>20</td>
<td>0.304</td>
<td>0.33%</td>
</tr>
<tr>
<td>40</td>
<td>0.3095</td>
<td>0.00%</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>( n_L )</th>
<th>( \int_S \frac{\sigma_{ij}}{p_o} , ds )</th>
<th>Deviation from Benchmark solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>0.746</td>
<td>1.36%</td>
</tr>
<tr>
<td>20</td>
<td>0.735</td>
<td>0.14%</td>
</tr>
<tr>
<td>40</td>
<td>0.736</td>
<td>0.00%</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>( n_L )</th>
<th>Simulation time (hours)</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>1.6</td>
</tr>
<tr>
<td>20</td>
<td>16.0</td>
</tr>
<tr>
<td>40</td>
<td>52.0</td>
</tr>
</tbody>
</table>
from the benchmark solution below 1%, a simulation time of 16 hours is required to complete the numerical analysis. However, the case of \( n_c = 10 \) despite slightly larger errors (maximum 1.60 %), requires only 1.6 hours to complete. Therefore, \( n_c = 10 \) is recommended to be used when computing facilities are limited.

**Temporal Discretization**

The finite element model developed in this study is time dependent. Therefore, it is essential to determine the maximum allowed FE time step (\( \Delta t \)). As mentioned previously, it is assumed that an exact solution may be achieved while \( \Delta t \) is adopted as low as 1/90 of a wave period. The objective of this section is to determine the FE time step so numerical errors are kept below 1% deviation from the exact solution. For this purpose, various time steps ranging from 1/9 to 1/90 of a wave period is examined hereafter. Simulation results are shown in Table (5). They demonstrate that a time step of \( \Delta t = 1/36 \) provides the sufficient numerical accuracy.

**Table 5.** Seabed Responses Around Pipeline for Various \( \Delta t \) while \( \alpha = 90^\circ \); \( n_p = 64; n_R = 12; n_L = n/a; n_c = 5 \)

<table>
<thead>
<tr>
<th>( \frac{T}{\Delta t} )</th>
<th>( \int_{s} \frac{p}{p_o} , ds )</th>
<th>Deviation from Benchmark solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>9</td>
<td>3.621</td>
<td>3.18%</td>
</tr>
<tr>
<td>18</td>
<td>3.700</td>
<td>1.07%</td>
</tr>
<tr>
<td>36</td>
<td>3.739</td>
<td>0.03%</td>
</tr>
<tr>
<td>54</td>
<td>3.741</td>
<td>0.03%</td>
</tr>
<tr>
<td>72</td>
<td>3.737</td>
<td>0.08%</td>
</tr>
<tr>
<td>90</td>
<td>3.740</td>
<td>0.00%</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>( \frac{T}{\Delta t} )</th>
<th>( \int_{s} \frac{\sigma'}{p_o} , ds )</th>
<th>Deviation from Benchmark solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>9</td>
<td>0.189</td>
<td>0.53%</td>
</tr>
<tr>
<td>18</td>
<td>0.190</td>
<td>0.00%</td>
</tr>
<tr>
<td>36</td>
<td>0.190</td>
<td>0.00%</td>
</tr>
<tr>
<td>54</td>
<td>0.190</td>
<td>0.00%</td>
</tr>
<tr>
<td>72</td>
<td>0.190</td>
<td>0.00%</td>
</tr>
<tr>
<td>90</td>
<td>0.190</td>
<td>0.00%</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>( \frac{T}{\Delta t} )</th>
<th>( \int_{s} \frac{\sigma'}{p_o} , ds )</th>
<th>Deviation from Benchmark solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>9</td>
<td>0.749</td>
<td>0.13%</td>
</tr>
<tr>
<td>18</td>
<td>0.749</td>
<td>0.13%</td>
</tr>
<tr>
<td>36</td>
<td>0.749</td>
<td>0.13%</td>
</tr>
<tr>
<td>54</td>
<td>0.749</td>
<td>0.13%</td>
</tr>
<tr>
<td>72</td>
<td>0.748</td>
<td>0.27%</td>
</tr>
<tr>
<td>90</td>
<td>0.750</td>
<td>0.00%</td>
</tr>
</tbody>
</table>

**Table 6.** Seabed Responses Around Pipeline for \( n_c \) while \( \alpha = 90^\circ \); \( n_p = 32; n_R = 8; n_L = n/a; \Delta t = 1/36 \)

<table>
<thead>
<tr>
<th>( n_c )</th>
<th>( \int_{s} \frac{\sigma'}{p_o} , ds )</th>
<th>Deviation from Benchmark solution</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1.240</td>
<td>45.26%</td>
</tr>
<tr>
<td>2</td>
<td>0.748</td>
<td>0.27%</td>
</tr>
<tr>
<td>3</td>
<td>0.750</td>
<td>0.00%</td>
</tr>
<tr>
<td>4</td>
<td>0.749</td>
<td>0.13%</td>
</tr>
<tr>
<td>5</td>
<td>0.749</td>
<td>0.13%</td>
</tr>
</tbody>
</table>

**VALIDATION**

Since the three-dimensional Finite Element model developed in the present study is new, it is necessary to validate the present model before proceeding to apply it to the 3-D wave-soil-pipeline interaction problem. For this purpose, a possible option is to consider the simplified case of the wave-induced response of a seabed in the absence of a structure. The exact solution for the interaction between a progressive wave and the naked seabed has been proposed by Hsu and Jeng [22].

It should be noted that the presented solution is for the case in which the seabed soil is not confined within a trench. Therefore, the numerical model should be modified so that the lateral trench wall boundary conditions in the \( \chi \) direction presented previously would be replaced by a periodic boundary condition, while the length of computational domain (\( \omega \)) is considered as one wave length. Variations of amplitudes of soil responses over the seabed depth (\( z \)), obtained from the present numerical model as well as the exact solution, are plotted in Fig. (5) for a set of soil and wave properties. It is apparent that numerical results excellently coincide with the previous analytical solution [22].
Fig. (5). Verification of numerical simulations from the present model against the analytical solution of Hsu and Jeng [22] for the wave-induced response of a seabed without a structure.

This is the numerical model developed to investigate the influence of wave angle of incidence on seabed responses near a submarine buried pipeline. Hence, it is essential to examine the performance of this model in a seabed with the presence of a pipeline. Although numerous investigations have applied the potential theory to derive an analytical solution for the problem of wave-seabed-pipe interaction, no exact solution using Biot consolidation theory is yet available in the literature even for a simplified two-dimensional case. On the other hand, to the author’s knowledge no experimental investigation has been carried out to consider three-dimensional influences. Therefore, it may be beneficial to verify numerical results against experimental data for the seabed response around a pipeline under the action of waves propagating normal to the structure. Such a simplified two-dimensional case has been experimentally studied in [23, 24], among others. Results presented in Sudhan et al. [24] appear to be extremely scattered. Therefore, experimental data from Turcotte et al. [23] is used herein to validate the numerical model.

Turcotte et al. [23] carried out a series of seven tests in Joseph H. DeFrees Hydraulics Laboratory, Cornell University. Experiments covered a range of short to long waves with a constant water depth. Seabed bed materials also remained unchanged over tests. Experiments were performed in a 17 m long, 0.76 m wide wave tank, where a 0.168 m PVC pipe was buried in trenched sand. Eight pore pressure transducers were instrumented around pipe circumference at every 45 degrees. The authors reported contours of pore pressure amplitudes in the vicinity of pipeline. Among the tested wave lengths, three cases representing short, intermediate and long waves have been adopted herein for the comparison between numerical and experimental data. Figs. (6)-(8) show pore pressure amplitudes, corresponding to these three wave lengths, around the pipeline circumference. Soil, pipe and wave properties are also indicated on these figures.

Fig. (6). Verification of numerical simulations from the present model against experimental data in Turcotte et al. [23] for short wave lengths.

Details of the Finite Element Model applied to simulate wave-soil-pipe interaction are presented in this section. Numerical experiments to justify the minimum required mesh resolution are performed. Further, the desired temporal discretization of time dependant FEA is examined. This was followed by a series of tests to validate the proposed numerical model. This included the verification of numerical results against an available analytical solution for the case of wave-induced seabed responses in the absence of a structure, as well as the comparison between numerical results and data from wave tank experiments of Cornell University. The latter covers the two-dimensional case of wave-seabed-pipeline interaction with waves approaching normal to the pipeline orientation. In both cases, excellent agreement was achieved. It was also found that the numerical model matches the ex-
experimental data better, when water waves are longer. The present three-dimensional model was also compared with an existing two-dimensional model. The 2-D model was found to be outperformed by the current model. In the next section, the proposed model will be used for a thorough parametric study on wave-induced seabed behaviours around pipelines, including the three-dimensional effects.

SEABED INSTABILITIES

Wave-Induced Shear Failure

Seabed soil failure, due to shear stresses, in the region close to the pipeline has been recognized as one of main mechanisms that will lead to the pipeline instability. In fact, the shear failure is the loss of soil ability to resist against shear stresses. This phenomenon is accompanied by the sliding of soil layers on each other and thus often by large horizontal displacements in the seabed deposit. The submarine pipeline, buried in the failed soil region, consequently undergoes large deformations and internal stresses, which in turn triggers the failure of the structure. Therefore, it is necessary to study the phenomenon of soil shear failure in the vicinity of a submarine pipeline. To date, several criteria have been proposed in the literature to justify the occurrence of soil shear failure. Among them, the Mohr-Coulomb shear failure criterion has been widely used by engineers in various geotechnical engineering applications. Thus, this criterion is adopted in the present study to investigate the soil instability as the result of excessive wave-induced shear stresses. Herein, a brief description on the Mohr-Coulomb criterion is presented.

Seabed stresses introduced and evaluated in previous sections were only due to the dynamic action of ocean wave pressure. However, the seabed soil is also under a static loading from its self-weight. It is important to note that soil instabilities are dominated by absolute seabed responses, which are formed by the superposition of static and dynamic (wave-induced) components of soil stresses. Therefore, it is essential to formulate absolute soil stresses before proceeding to describe the shear failure criterion. Considering a soil element located at the elevation \( z \) below the seabed surface, the state of static overburden effective stresses induced by the buoyant weight of soil column above this element is illustrated in Fig. (45b). Soil overburden effective stresses are, therefore, as:

\[
\sigma'_{ox} = \sigma'_{oy} = K_o (\gamma_s - \gamma_w)z \\
\sigma'_{oz} = \gamma_s z = (\gamma_s - \gamma_w)z 
\]

where, \( \sigma'_{ox}, \sigma'_{oy} \) and \( \sigma'_{oz} \) are static normal effective stresses in the \( x-, y-, \) and \( z- \) directions, respectively; \( \gamma'_s \) is the submerged unit weight of the soil; \( \gamma_s \) and \( \gamma_w \) are unit weights of soil and water, respectively; and \( K_o \) is the coefficient of earth lateral pressure. As throughout this text, a negative value represents a compressive stress mode. It is also worthy to point out that the soil self-weight imposes no shear stresses in the \( x-, y-, \) and \( z- \) planes on the soil element. Finally, absolute soil stresses are:

\[
\bar{\sigma}_x = \sigma'_x + K_o (\gamma_s - \gamma_w)z \\
\bar{\sigma}_y = \sigma'_y + K_o (\gamma_s - \gamma_w)z \\
\bar{\sigma}_z = \sigma'_z + (\gamma_s - \gamma_w)z 
\]

Absolute \( x-, y-, \) and \( z- \) effective stresses can further be used to obtain absolute principal effective stresses through the same methodology as described by equations (35)-(36).

To describe the shear failure criterion, let us assume an arbitrary plane within the soil element, normal to which an absolute effective stress of \( \bar{\sigma}' \) is acting in the compressive mode. At the same time, the maximum absolute shear stress that acts within this plane is assumed to be represented by \( \bar{\tau} \). According to Coulomb’s criterion, the shear stress that brings the soil to the state of shear failure \( (\bar{\tau}_f) \) is related \( \bar{\sigma}' \) by:

\[
\bar{\tau}_f = -\bar{\sigma}' \tan(\phi_f) 
\]

in which, \( \phi_f \) is the soil internal friction angle, which is a property of seabed soil. The shear failure occurs if the absolute soil shear stress exceeds \( \bar{\tau}_f \). By defining the stress angle \( (\phi) \), with analogy to the equation (40), as the ratio of absolute shear stress to the absolute normal effective stress, the shear failure criterion can be expressed by:

\[
\phi \geq \phi_f 
\]

On the other hand, the state of soil stress on any arbitrary plane falls within the region confined by three-dimensional Mohr circles. Therefore, the utmost stress angle for a given state of soil stress is limited to the slope of a line that is tangent to the greatest of Mohr circles, as plotted in Fig. (9). The stress angle is therefore:

\[
\phi = \sin^{-1}\left(\frac{\bar{\sigma}'_{33} - \bar{\sigma}'_{11}}{\bar{\sigma}'_{11} + \bar{\sigma}'_{33}}\right) 
\]
where, $\overline{\sigma}_{11}$ and $\overline{\sigma}_{33}$ are respectively major and minor absolute principal effective stresses, as illustrated. Equations (41) and (42) can be used to justify the occurrence of shear failure in a seabed soil.

$$\phi_0 = \sin^{-1} \left( \frac{\sigma'_{ox} - \sigma'_{oz}}{\sigma'_{ox} + \sigma'_{oz}} \right) = \sin^{-1} \left( \frac{1 - K_o}{1 + K_o} \right)$$

(43)

On the other hand, the soil coefficient of lateral earth pressure can be related to the internal friction angle by the formula proposed by Jacky (1944):

$$K_o = 1 - \sin(\phi_f)$$

(44)

Substituting equation (44) into (43), one will get:

$$\sin \phi_0 = \frac{\sin \phi_f}{2 - \sin \phi_f}$$

(45)

Polous [25] reported that the internal friction angle of a sandy seabed ranges from 20° to 30° [26]. In this range, it is possible to accurately fit a linear relation into the equation (45). However, let us approximate the equation (45) in $20^\circ < \phi_f < 30^\circ$ by a simpler linear relation, which is of unit slope:

$$\phi_0 = \phi_f - C$$

(46)

where, $C$ is a constant that can be considered to be around 9.5° (see Fig. (10)). Inspired by the relation (46), it is then possible to define a wave-induced perturbation in soil stress angle such as $(\Delta \phi)_\text{wave} = \phi - \phi_0$. Such wave-associated perturba-

**Fig. (9).** The Mohr-Coulomb shear failure criterion.

Before proceeding to the next section, it is also useful to explain to which extent static and dynamic components of seabed loading contribute to the potential of soil shear failure. For this purpose, consider a soil element within the seabed without the presence of wave dynamic loading. Since, there are no shear stresses acting on surfaces of this soil element, $\sigma'_{ox}$, $\sigma'_{oy}$, and $\sigma'_{oz}$, also serve as principal effective stresses under the static loading. Substituting these stresses into the equation (42), the at-rest stress angle corresponding to the initial geostatic state of soil stresses may be defined and simplified as:

$$\phi_0 = \sin^{-1} \left( \frac{\sigma'_{ox} - \sigma'_{oz}}{\sigma'_{ox} + \sigma'_{oz}} \right) = \sin^{-1} \left( \frac{1 - K_o}{1 + K_o} \right)$$

(43)

On the other hand, the soil coefficient of lateral earth pressure can be related to the internal friction angle by the formula proposed by Jacky (1944):

$$K_o = 1 - \sin(\phi_f)$$

(44)

Substituting equation (44) into (43), one will get:

$$\sin \phi_0 = \frac{\sin \phi_f}{2 - \sin \phi_f}$$

(45)

Polous [25] reported that the internal friction angle of a sandy seabed ranges from 20° to 30° [26]. In this range, it is possible to accurately fit a linear relation into the equation (45). However, let us approximate the equation (45) in $20^\circ < \phi_f < 30^\circ$ by a simpler linear relation, which is of unit slope:

$$\phi_0 = \phi_f - C$$

(46)

where, $C$ is a constant that can be considered to be around 9.5° (see Fig. (10)). Inspired by the relation (46), it is then possible to define a wave-induced perturbation in soil stress angle such as $(\Delta \phi)_\text{wave} = \phi - \phi_0$. Such wave-associated perturba-

**Fig. (10).** Linear approximation of relation between geostatic stress angle and internal friction angle.

It should be pointed out that, as it will be shown later, the stress angle perturbation often alters much beyond the value of 9.5 degrees as the result of a change in water wave properties. In fact, a small change in wave characteristics can be so influential in altering the state of soil stresses from the compressive to the tensile mode. In contrary, soil properties are often found to produce much smaller effects on perturbations of stress angle. However, the influence of most soil properties is still comparable with 9.5 degrees. Therefore, both soil and wave properties will be considered in this research to carry out a parametric study on the stress angle. More details of the parametric study will be presented in coming sections.

**Wave-Induced Soil Liquefaction**

Another important mechanism for the instability of submarine buried pipelines is the seabed liquefaction. The liquefaction, as defined in [27], is the transformation of a granular material from a solid to a liquefied state as a consequence of increase in pore water pressure and reduction in compressive effective stress [28, 29]. In fact, a wave-induced increase in pore pressure can be strong enough to cause the effective stress to vanish or even go into the tensile mode. This is triggered by the loss of grain to grain contacts in the soil matrix and further results in the soil skeleton becoming incapable of carrying any external load, apart from its self-weight. Hence, a submarine pipe will sink or float within the liquefied seabed under the action of pipe buoyant weight. Large vertical
deformations and stresses that are associated with the sinking/floatation of a buried structure, finally, can lead to its failure. It is also possible for the pipeline to be dragged within the liquefied soil due to the presence of bottom currents and thus to undergo large horizontal deformations. To avoid a catastrophe resulting from the pipeline failure, it is essential to investigate the potential of soil liquefaction in the vicinity of this structure. For this purpose, a reliable liquefaction criterion has to be applied.

Among available studies, researchers have considered various criteria to justify the occurrence of seabed soil liquefaction. Generally speaking, a first group of researchers has been concerned with the “reduction in effective stresses” as the liquefaction criterion. Among those, Okusa [30] suggested that a sandy bed becomes liquefied if the absolute vertical effective stress steps into the tensile (positive) phase. That is:

$$\sigma_z^v \geq 0$$

It should be pointed out that seabed effective stresses are initially in the compressive mode under calm sea conditions as the result of the weight of overlying soil layers. Therefore, substituting the absolute vertical effective stress from equation (39), the aforementioned liquefaction criterion becomes as:

$$\sigma_z^v + (\gamma_s - \gamma_w)z \geq 0$$

Later, Tsai [31] modified this criterion by considering the average of absolute effective stresses, as:

$$\frac{1}{3} (\sigma_x^v + \sigma_y^v + \sigma_z^v) + \frac{1}{3} (\gamma_s - \gamma_w)z \geq 0$$

A common property of the work Okusa [30] and Tsai [31] is the use of effective stresses. However, the fieldwork by Zen and Yamazaki [32] revealed that field measurements of soil effective stresses involve significant inaccuracies, when the soil is near to the liquefaction state. Therefore, they suggested the use of a liquefaction criterion based on the excess pore pressure. In fact, Zen and Yamazaki [33] applied the underlying assumptions of one-dimensional consolidation theory to replace the change of vertical effective stress from the geostatic state to the absolute value (i.e. wave-associated vertical effective stress) by the excess pore pressure. Hence, the equation (48) was approximated by the following criterion:

$$\bar{\sigma}_z^v = p_{excess} + (\gamma_s - \gamma_w)z \geq 0$$

where, the excess pore pressure is:

$$p_{excess} = p - p_{bed}$$

The advantage of this method is the use of wave-induced pore pressure, which is found to be reliably measured even in nearly liquefied soils. Later, Jeng [34] extended this approximate framework to three-dimensions with an analogy to the equation (49). They have also shown that their liquefaction criterion, formulated in equation (52), reproduces field observations of Zen and Yamazaki [32] better than other aforementioned criteria. Therefore, this criterion is adopted in the present study to justify the occurrence of seabed liquefaction in the vicinity of submarine buried pipelines.

$$p_{excess} + \frac{1}{3} (1 + 2K_o) (\gamma_s - \gamma_w)z \geq 0$$

The adopted liquefaction criterion is shown in Fig. (11) for the case of a naked seabed in the absence of a pipeline. As it is illustrated, the excess pore pressure becomes positive in seabed under the wave trough. This is because the wave dynamic pressure ($p_{bed}$) is attenuated within the porous bed and the wave-induced pore pressure ($p$) is, therefore, a fraction of wave pressure. Hence, under the wave trough, where the pressure is in suction (negative) mode, $p_{excess} = p - p_{bed}$ is positive. However, it should be pointed out that this illustration is an indicative idealized case. In reality, where a phase lag also exists between the pore pressure and the seabed loading, a positive excess pore pressure can be observed distant from the wave trough. In particular, such a phase lag can be extremely significant when the structure exists. The soil liquefaction occurs under stormy conditions when the excess pore pressure exceeds the compressive mean geostatic stress, which is linearly increasing over the seabed depth. Therefore, a liquefied state of soil is observed in a layer immediately below the seabed surface, as indicated. It should be noted that the seabed surface may be always considered to be liquefied.

**Fig. (11).** The concept of wave-induced liquefaction after Zen and Yamazaki [33].

**PARAMETRIC STUDY**

In this section, a parametric study on seabed instabilities is proposed with an analogy to the parametric study previously carried on wave-induced seabed responses. For this purpose, potentials of soil liquefaction and shear failure around a pipeline are studied. The excess pore pressure and the stress angle are respectively considered as indicators of liquefaction and shear failure potentials and successively
Three-Dimensionalities of Ocean Waves

on the wave-induced excess pore pressure \( p_{\text{excess}} \) and the stress angle \( \phi \) would not be an exception. In particular for the stress angle, however, the spatial and temporal distribution, though being periodic, is not linearly sinusoidal, as illustrated in Fig. (12). The complex distribution pattern of stress angle, nevertheless, is of little or no importance, since it is the peak value of stress angle \(|\phi|\), which is the key factor to evaluate the risk associated with the shear failure. This peak value is referred to as the amplitude of stress angle, throughout this text.

Finally, since the wave-loading is of a periodic nature both in time and space, both the stress angle and excess pressure also follow similar periodic patterns. Nevertheless, it will be shown that spatial and temporal distributions of these variables are not simply sinusoidal. Therefore, such distributions will be discussed prior to going further into the parametric study. From that point onward, amplitudes of the stress angle and excess pore pressure will be the subject of parametric study. It is worthy of note that peak or the most critical values of these parameters over a wave period is referred to by the term amplitude, in this text.

Three-Dimensionality of Ocean Waves

One of the key objectives of developing the three-dimensional finite element model is to determine the influence of wave obliquity on the potential of seabed instability near the pipeline. No study is yet available in the literature to address such effects. On the other hand, it is vital to coastal geotechnical engineers to determine influences of wave direction on the so-called amplitude of stress angle \(|\phi|\) and excess pore pressure \(|p_{\text{excess}}|\). Fig. (13) shows the distribution of \(|\phi|\) around the pipeline circumference for various wave obliquities. It is evident that sheltered and naked sides of a pipeline behave symmetrically when ocean waves are propagating parallel with the pipeline (\(\alpha=0^\circ\)). That is \(\theta=90^\circ\) and \(270^\circ\) serve as axes of symmetry for the illustrated distribution pattern (see filled circles). The symmetric behaviour, however, is not applicable when the pipe is exposed to an oblique wave. The obliquity-induced asymmetry is more significant at the lower half of the pipe perimeter (\(180^\circ < \theta < 360^\circ\)). In the presented example, the amplitude of the stress angle is found to vary mainly monotonically with \(\alpha\), in each of the circumferential spans formed between the six illustrated inversion nodes/regions. The direction of this monotonic trend reverses among adjacent circumferential spans.

As discussed earlier, the wave obliquity affects seabed responses through the following mechanisms: (1) three-dimensional geometry-based influences and (2) effects of wave direction on the amplitude of seabed responses. The former requires variations of pore pressure and soil stresses to be periodic over spans of the length \(L/\cos(\alpha)\) along the pipe longitudinal axis, as well as, over the wave period. In the same manner, key parameters to justify the potential of soil instabilities, \(p_{\text{excess}}\) and \(\phi\), would not be an exception. In particular for the stress angle, however, the spatial and temporal distribution, though being periodic, is not linearly sinusoidal, as illustrated in Fig. (12). The complex distribution pattern of stress angle, nevertheless, is of little or no importance, since it is the peak value of stress angle \(|\phi|\), which is the key factor to evaluate the risk associated with the shear failure. This peak value is referred to as the amplitude of stress angle, throughout this text.

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this regard, Table (7) presents the maximum value of stress angle over the pipeline perimeter ($\phi_{\text{max}}$), for several simulated cases. In this table, the value of $\phi_{\text{max}}$ corresponding to waves propagating parallel with and normal to the pipeline are respectively shown by $\phi_{\text{max}}^0$ and $\phi_{\text{max}}^{90}$; meanwhile $\phi_{\text{max}}^{\text{cr}}$ stands for the most critical value of stress angle that a wave of an arbitrary direction can generate; finally, $\alpha_{\text{cr}}$ is the wave direction, for which $\phi_{\text{max}}^{\text{cr}}$ is observed. It should be noted that for some cases $\phi_{\text{max}}^{\text{cr}}$ can be more than 30° larger than $\phi_{\text{max}}^{90}$, which represents a two-dimensional case (see last row of table). At the same time, although other cases show much smaller difference, it should be still remembered from the previous section that the soil will fail if the waves could increase the stress angle only about 9.5 degrees. Therefore, any three-dimensional effect that can boost up the stress angle even a few degrees can still be considered as being significant. On the other hand, an inspection into values of $\alpha_{\text{cr}}$ in the table shows that the two limiting cases of $\alpha=0^\circ$ or $90^\circ$ are not always responsible for the most critical situation.

Table (7). The maximum of stress angle ($\phi_{\text{max}}$) experienced around pipeline for a variety of soil and wave properties (unless explicitly expressed within the table, soil, wave and pipe properties are as $h=25$ m, $T=8.36$ s, $L=100$ m, $G=10^6$ Pa, $\mu=0.4$, $n=0.3$, $k=10^{-3}$ m/s, $S=0.97$, $D=1.0$ m, $w/D=4.0$, $d/D=2.0$, $B/d=0.5$, $K_o=0.5$, $\gamma_s=1.969\gamma_w$, and $H=5.0$ m).

<table>
<thead>
<tr>
<th>Soil/wave Properties</th>
<th>$\phi_{\text{max}}^0$</th>
<th>$\phi_{\text{max}}^{90}$</th>
<th>$\phi_{\text{max}}^{\text{cr}}$</th>
<th>$\alpha_{\text{cr}}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$G=0.1\text{MPa}$</td>
<td>24.8</td>
<td>26.6</td>
<td>26.7</td>
<td>67.5</td>
</tr>
<tr>
<td>$G=100\text{MPa}$</td>
<td>32.2</td>
<td>32.7</td>
<td>32.8</td>
<td>45.5</td>
</tr>
<tr>
<td>$k=10^{-4}$ m/s</td>
<td>28.4</td>
<td>29.0</td>
<td>29.0</td>
<td>90.0</td>
</tr>
<tr>
<td>$k=10^{-2}$ m/s</td>
<td>24.8</td>
<td>26.7</td>
<td>26.8</td>
<td>67.0</td>
</tr>
<tr>
<td>$S=91%$</td>
<td>40.1</td>
<td>41.2</td>
<td>41.2</td>
<td>90.0</td>
</tr>
<tr>
<td>$S=99%$</td>
<td>25.4</td>
<td>27.2</td>
<td>27.2</td>
<td>90.0</td>
</tr>
<tr>
<td>$T=12$ sec, $h=12.5$ m</td>
<td>59.6</td>
<td>53.4</td>
<td>60.1</td>
<td>22.5</td>
</tr>
<tr>
<td>$T=10$ sec, $h=12.1$ m</td>
<td>72.6</td>
<td>57.4</td>
<td>90.0</td>
<td>22.5</td>
</tr>
</tbody>
</table>

Fig. (14) illustrates that the influence of wave direction on the amplitude of excess pore pressure is not significant. Consequently, the potential of complete liquefaction is likely to remain unchanged even when the waves are approaching the pipeline from an oblique angle. Therefore, unlike the potential of shear failure, a two-dimensional model is sufficient to justify the occurrence of complete liquefaction around the pipeline. However, the amplitude of $p_{\text{excess}}$, which can be obtained from a 2-D simulation, should be considered along with the three-dimensional geometry-based influences of wave obliquity on the spatial distribution of soil responses, as previously discussed.

Influences of Seabed Soil Properties

Modulus of Soil Shear Stiffness

The influence of soil shear stiffness on the pore pressure and soil stresses has been studied earlier in this section. In fact, the shear modulus was found to have significant effects on the wave-associated momentary seabed behaviour. Therefore, it is essential to also examine the influence of this parameter on the potential of seabed soil instabilities. As plotted in Figs. (15),(16), amplitudes of both excess pore pressure and stress angle increase when the seabed material is stiffer. Therefore, a stiff porous bed is more vulnerable to both complete liquefaction and shear failure.

To determine the critical value of excess pore pressure, corresponding to the onset of soil liquefaction, it is possible to normalize the relation (52) by the amplitude of mudline pressure. Hence, the seabed will be liquefied if the non-dimensional excess pore pressure exceeds the critical value:
The normalized critical excess pore pressure varies over the pipeline circumference, since so does the vertical coordinate $z$. It should be pointed out that in the evaluation of critical excess pore pressure, the pipe cross-section is assumed to be of an equivalent unit weight similar to that of porous bed. In fact, this assumption is reasonable for the typical range of materials and diameters used for the construction of underwater pipelines, as well as, for fluids usually being transported though a submarine pipe. In this parametric study, the coefficient of lateral earth pressure of $K_o = 0.5$, and soil unit weight of $\gamma_s = 1.969 \gamma_w$ are often used to evaluate the critical excess pore pressure. This unit weight is the same as that observed in field measurements of Zen and Yamazaki [32]. A wave height of about $H = 5$ m is also often used, which may be considered as a stormy condition for the range of shallow water depths, in which the pipe burial is necessary. However, a non-breaking condition for wave waters is still ensured. Although a variety of wave characteristics, i.e. wave length and wave period, could be chosen, for most cases the wave regime is deliberately chosen so the soil initially remains well away from liquefaction. This will allow us to show a picture of soil/trench/pipeline parameters that may be significant enough to cause a shift from this stable situation to a liquefied state of soil.

In contrast to Fig. (15), where the excess pressure is still far below the critical value corresponding to $\eta = 0.60$ ($H = 5.35$ m), the stress angle in Fig. (16), is found to go beyond the soil internal friction angle. In fact, prior to exerting the wave loading, the stress lays at the value of $\phi_o$ indicated on the graph. Considering the action of waves on a soil of $G = 10^6$ Pa, the stress angle still falls between its initial geostatic value and the soil internal friction angle. However, by increasing the soil stiffness to $G \geq 10^7$ Pa the soil will undergo shear failure. Under these circumstances, the seabed at the lateral sides of pipeline, in $0^\circ < \theta < 45^\circ$, $135^\circ < \theta < 225^\circ$, and $315^\circ < \theta < 360^\circ$, will fail. It should be pointed out that by using higher wave heights in numerical simulations, the unstable soil region around structure could even merge to cover the pipe crest as well. It is interesting to note that patterns of distributions of both excess pore pressure and stress angle remain alike for all examined soil shear moduli.

\[
\frac{p_{ex}}{p_o} = \frac{-z}{3p_o} (1 + 2K_o) (\gamma_s - \gamma_w) = -\eta z
\]

where, $\eta$ is a coefficient which is a function of lateral earth pressure coefficient, soil and water unit weights and the amplitude of mud-line pressure.

The Degree of Saturation

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On the other hand, the distribution pattern of excess pore pressure is found to remain the same for all cases. However, rather different behaviour patterns have been observed for stress angle in fine and coarse materials. In fact, maximum values of stress angle are located at the lower lateral sides of the pipeline, $\theta = 190^\circ$ and $350^\circ$ for fine sediments, while points of high risk of shear failure are at the upper half of the pipe, $\theta = 45^\circ$ and $135^\circ$, in gravel and coarse sands.

\[
p_{ex}/p_o = -\eta z
\]

The Degree of Saturation

It is common for most marine sediments to contain a small percentage of air, and thus showing a degree of satura-
tion between 0.90 and 1.00. However, even small amounts of air significantly reduce the compressibility of pore fluid and consequently influence seabed responses. Therefore, it is important to examine the effects of soil saturation on the instability of seabed soil, in the vicinity of a submarine buried pipeline. For this purpose a range of nearly saturated soils has been adopted to carry out the parametric study. Fig. (19) demonstrates how significantly an increase in the soil air content will change the wave-associated excess pore pressure and the risk of complete liquefaction, compared with other soil characteristics previously studied. In addition to the critical value of excess pore pressure corresponding to a wave height of 5 m, \( p_{cr} \) corresponding to an exaggerated wave height of 8 m \( (\eta = 0.4) \) is also plotted in the figure. It can be seen that for \( S = 91\% \), the excess pore pressure coincides with this critical value and thus the seabed liquefies.

As shown in Fig. (20), the soil stress angle also shifts up in less-saturated soils, with the 95\% saturated sand being the first to show shear failure near the pipeline lateral sides. The failure region extends by further increasing the air content. This continues so that for a 91\% saturated soil, the stress angle at every point apart from the region below the pipeline, goes beyond the soil internal friction angle. It should be pointed out that, generally speaking, the seabed soil in the vicinity of the pipeline base at \( \theta = 270^\circ \) is often in the most stable situation, with the stress angle always remaining almost unchanged due the action of waves.

Influences of Trench and Pipeline Geometries

Trench Depth

Although the present numerical model is capable of simulating any arbitrary trench geometry and pipe burial depth, in the present parametric study the pipeline is assumed to be buried halfway through the trench depth. Therefore, by varying the trench depth, influences of both trench depth and pipe burial depth are studied simultaneously. Such an assumption is suitable for practical engineering purposes, since due to the high cost of an underwater excavation, the seabed will be trenched only as deep as to just comply with the desired pipe burial depth. As illustrated in Fig. (21), the amplitude of wave-associated excess pore pressure dramatically increases in deeper trenches. This is because the mudline pressure is much attenuated in a deep trench, as discussed previously. However, in contrary to all previously presented cases, an increase in the pore pressure may not be immediately interpreted as a higher potential of complete liquefaction. This seemingly surprising statement stems back to the fact that while the pipeline is buried deeper within the trench, geostatic overburden stresses around it and thus the critical excess pore pressure will also increase. These stresses are in fact a measure for the weight of the soil column above the pipeline and their action is to resist against soil liquefaction as discussed while introducing the liquefaction criterion. Under these circumstances, one way to study the potential of seabed liquefaction is to normalize the excess pore pressure by its critical value.

A wave height and soil unit weight have been chosen so that \( \eta = 0.50 \) is used herein to evaluate the critical excess pore pressure and to produce the plot of Fig. (22). Interesting features can be interpreted from the presented results. That
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is, moving from shallow burial depths (and trench depths) to deep burial depths, the geostatic static stress gradually become sufficient enough to overcome the increasing trend of excess pore pressure. Hence, graphs of $p_{\text{excess}}/p_{\text{cr}}$ gradually get closer to each other when increasing the burial depth. This continues until $d/D = 3.0$, after which $p_{\text{excess}}/p_{\text{cr}}$ even drops down by further increasing the burial depth. This feature implies that despite the traditional belief, increasing the pipe burial depth does not always lead to a more secure protection against soil liquefaction. Instead, there exists a critical burial depth, after which an increase in pipeline stability may be observed. However, a significant difficulty associated with this behaviour is that further increasing the burial depth seems no longer economical, considering that even for $d/D = 3.5$ the potential of liquefaction is still much more than that for $d/D = 1.50$. Therefore, it may be beneficial to seek other protection methods such as using a cover layer to protect the pipeline against soil liquefaction, rather than excessively increasing the burial depth.

Another important feature of the results presented is that the most critical values of $p_{\text{excess}}/p_{\text{cr}}$ are always observed in the lower half of the pipeline. This means that in the case of an occurrence of soil instability, it is the soil at the lower half of pipeline that liquefies at the first place. However, the excess pore pressure for the presented cases still merely reaches 35% of its critical value at the lower half of the pipeline. On the other hand, the upper half of structure seems to be securely stable against liquefaction, especially when a trench is shallow. The significant difference between the potential of liquefaction at lower and upper parts of the pipe gradually vanishes in deeper trenches.

Despite the behaviour of liquefaction potential, the submarine pipeline is found to be more likely protected against shear failure, when buried in a deeper trench. This is the result of stress angle decreasing almost everywhere around a pipeline when $B$ and $d$ are increased, as shown in Fig. (23). However, a more complicated relation between $d$ and $\Phi$ is observed near the pipe crest ($\theta = 90^\circ$).

A trench width ranging from 1.5 to 4.0 times of the pipeline diameter is investigated in this study. Amplitudes of wave-associated excess pore pressure are plotted in Fig. (24). The illustration shows that values of non-dimensional excess pore pressure decline by widening the trench geometry. The influence of trench width slowly vanishes in wider trenches, where graphs of excess pore pressure gradually merge on each other. However, the effect of trench breadth does not completely diminish in the range of examined trench widths.

Fig. (23). The distribution of $|\Phi|$ around pipeline circumference for various $d/D$.

(Soil, wave, trench and pipe properties are as in Fig. (22), $K_c = 0.5$, $\gamma_s = 1.969\gamma_w$ and $H = 5.0$ m)

**Trench Width**

A trench width ranging from 1.5 to 4.0 times of the pipeline diameter is investigated in this study. Amplitudes of wave-associated excess pore pressure are plotted in Fig. (24). The illustration shows that values of non-dimensional excess pore pressure decline by widening the trench geometry. The influence of trench width slowly vanishes in wider trenches, where graphs of excess pore pressure gradually merge on each other. However, the effect of trench breadth does not completely diminish in the range of examined trench widths.

Fig. (25) illustrates the distribution of stress angle around the pipeline. The stress angle at the pipe bottom ($\theta = 270^\circ$) is merely more than the static value, imposed by the soil submerged weight. On the other hand, the risk of shear failure is highest around $\theta = 35^\circ$ and $145^\circ$, where the stress angle is just below the soil internal friction angle of seabed soil. Furthermore, widening the trench significantly increases the stress angle almost everywhere else around the pipeline.
However, a more complicated behaviour is observed near the potential shear failure regions, marked by A and B in Fig. (25), as the stress angle is the highest for \( w/D = 2.5 \).

**Fig. (24).** The distribution of \( |p/p_o| \) around pipe perimeter for various \( w/D \).

**Fig. (25).** The distribution of \( |\text{a}| \) around pipeline circumference for various \( w/D \).

**Pipeline Diameter**

The potential and pattern of soil liquefaction are expected to be different between pipelines of small and large diameters. To demonstrate this, Fig. (26) shows the distribution of excess pore pressure around a pipeline perimeter for various pipe diameters. In this regard, the upper and lower halves of the pipeline are found to behave in a different way. In fact, close to the crest of the structure, \( |p_{\text{excess}}/p_o| \) drops down by increasing the pipe diameter; while, an opposite trend is in the vicinity of the pipeline bottom. However, these results are not sufficient to justify how the potential of soil liquefaction varies with the pipe diameter. This is because by enlarging \( D \), geostatic overburden stresses will also drop at the upper half of the structure, while they will increase at its lower. Therefore, it is essential to examine the ratio between the excess pore pressure and its critical value.

**Fig. (26).** The distribution of \( |p_{\text{excess}}/p_o| \) around pipeline circumference for various pipe diameters.

**Fig. (27).** The potential of soil liquefaction around pipeline for various pipeline diameters.

The distribution pattern of \( |p_{\text{excess}}/p_{\text{cr}}| \) around the pipeline is plotted in Fig. (27). \( |p_{\text{excess}}/p_{\text{cr}}| \) is found to have a similar behaviour as \( |p_{\text{excess}}/p_o| \). This behaviour was in fact expected, since generally speaking the pipeline is a slender structure. Hence, a change in its diameter may not impose a significant effect on \( \text{"a"} \) coordinates and thus \( p_{\text{cr}} = \eta \text{"a"} \) of points located on its circumference.

Another feature of the potential of soil liquefaction near the structure is that as the diameter decreases, a more uniform distribution of \( |p_{\text{excess}}/p_{\text{cr}}| \) around the pipe perimeter is observed. Therefore, in the event of soil instability, it is likely for a slender pipeline to be completely surrounded by liquefied soil. Consequently, a slender pipeline could sink or float within the bed, depending on the magnitude of seepage force and pipeline weight. However, the significant difference between \( |p_{\text{excess}}/p_{\text{cr}}| \) at the lower and upper parts of a large-diameter pipe requires extremely steep waves (i.e. a large \( \eta \)) to liquefy the seabed at the pipe crest, while the pipe
bottom is capable of being liquefied much earlier. This uneven liquefaction pattern allows the structure only to sink within the bed, since the soil in the upper half of the structure may not be liquefied in most cases. However, strict knowledge of all acting and reacting forces on the structure is necessary to draw a strong conclusion. Further, the excess pore pressure in the presented case is still far beyond the critical liquefaction limit \( p_{cr} \) for a storm of \( H = 5.35 \text{ m} \) \((\eta = 0.6)\), which was assumed to plot the Fig. (27).

**Influences of Ocean Wave Properties**

**Wave Period**

It has been previously shown in the earlier section that an increase in the wave period \( T \) forcefully shifts up the normalized wave-associated normal and shear stresses within the seabed soil. This effect has been attributed to the characteristic time required by the influence of mudline loading to penetrate into the seabed, in comparison with the period (frequency) of such a loading. It is important to examine the existence of a similar behaviour in the distribution of excess pore pressure around a pipeline. Therefore, several wave events of the same wave length \( (L = 100 \text{ m}) \) but of variable frequency have been considered herein. These frequencies correspond to wave periods of 8.36 s to 14 s, which are common in the ocean environment. It is worth being reminded that the wave dispersion equation requires wave events of longer periods to take place in shallower water depths. According to linear wave theory, therefore, the amplitude of mudline pressure \( p_o \) is larger under these circumstances. However, this effect is excluded from the parametric study on the excess pore pressure, when it is normalized by the amplitude of wave pressure at the mudline. Fig. (28) indicates that this normalized amplitude of excess pore pressure increases as does the wave period. The effect of \( T \), however, gradually fades away, as the excess pore pressure ratio goes beyond \( T = 12 \text{ s} \) to 14 s. This phenomenon implies that loadings of period of more than 12 s can no longer be considered as “quick” compared with the characteristic time that soil around the pipeline requires to adapt with the wave loading.

Once again, the occurrence of complete liquefaction around a pipeline, nevertheless, should be justified against non-dimensional geostatic overburden stresses. However, since \( p_{excess}/p_o \) varies as the wave period changes, it is appropriate to examine \( p_{excess}/p_{cr} \) to study the potential of soil liquefaction. As illustrated in Fig. (29), the lower part of the pipeline \((180^\circ < \theta < 360^\circ)\) falls within the liquefied region for the wave period of 14 s and wave height of 5.0 m, since the excess pore pressure goes beyond its critical value \( (p_{cr}) \). The increased potential of liquefaction in longer wave periods is mainly because of the fact that low frequency waves are associated with excessively larger values of mudline loading.

**Fig. (28).** The distribution of \( |p_{excess}|/p_o \) around pipe perimeter for various \( T \).

**Fig. (29).** The potential of soil liquefaction around pipe perimeter for various \( T \). \((K_o = 0.5 \text{ and } \gamma_s = 1.969\gamma_w)\).

**Fig. (30).** The distribution of \( |\phi| \) around pipeline circumference for various wave periods.

Unlike the potential of liquefaction, soil shear failure occurs around the pipeline even for much shorter wave periods. Referring to Fig. (30), a 5.0 m wave height triggers the soil shear failure in the upper part of the pipeline as well as most of its lower part, in wave periods of equal or greater than 10 seconds. Nonetheless, the seabed soil under the pipe base \((\theta = 270^\circ)\) interestingly remains strongly stable against shear failure, in all examined cases. It is important to note that a
stress angle (\(\phi\)) between 0° and 90° portrays a Mohr circle with normal stresses completely being in a compressive phase. Meanwhile as \(\phi\) increases by increasing \(T\), the Mohr circle shifts towards the tensile phase. A Mohr circle with a tensile mode of stress on any plane is indicated by \(\phi=90°\) in the present illustration. Knowing that sandy beds, which are non-cohesive, may not resist against a tensile stress, such a kind of instable situation is observed for \(T=12\) s and 14 s, as plotted.

**Water Depth**

Fig. (31) illustrates the influence of water depth on normalized amplitudes of wave-induced excess pore pressure. It should be pointed out that a decrease in water depth is associated with an increase in the amplitude of the mudline wave pressure (\(p_o\)). However, since the excess pore pressure, herein, is normalized by the amplitude of mudline pressure, this effect is not included in results presented in Fig. 68. Instead, as discussed earlier in this section, as the wave enters shallower water depths, its wave length decreases. Thus, the geometry of wave loading on the seabed alters and thus the normalized excess pore pressure will be influenced. As illustrated, the normalized excess pore pressure (\(|p_{\text{excess}}|/p_o\)) will increase as shallower water depths are chosen. Meanwhile, the unfortunate combination of increases in both \(|p_{\text{excess}}|/p_o\) and \(p_o\) for shallow water depths, results in the pipeline being extremely vulnerable to the soil liquefaction in shallow waters, as can be deduced from Fig. (32). It is observed that for \(h=5.38\) m and \(H=5\) m, the \(|p_{\text{excess}}|\) exceeds the mean static overburden stress (\(p_{cr}\)) everywhere in the lower half of pipeline. Therefore, it is predicted that the soil in the vicinity of the lower part of the structure will be completely liquefied under this wave regime. At the same time, the threat for soil shear failure is even more substantial, since the stress angle in the upper half of the pipeline goes beyond the soil internal friction angle for all examined water depths, as depicted in Fig. (33). It should be pointed out that Mohr’s circles will shift into the tensile zone for both \(h=5.38\) m \(h=7.61\) m, as the stress angle reaches 90°. This is due to the mud-line dynamic loading that becomes excessively large in shallow waters.

**CONCLUSIONS**

In this study, a three-dimensional numerical model for the wave-induced seabed response around a buried pipeline is proposed. Since there is no 3D experimental data available, the present model is reduced to 2D case or the 3D case with absence of a pipeline. The comparison with the previous theoretical and experimental work validated the present model.

Based on the newly 3D model, the effects of wave and soil characteristics on the wave-induced seabed instability, including shear failure and liquefaction, are discussed. Based on the parametric study presented, the following conclusions can be drawn:

1. The concept of wave-induced perturbation of soil stress angle has been introduced for the first time in this study. It was found that the seabed undergoes shear failure when the soil stress angle increases 9.5 degrees from its geostatic value, due to the action of water waves.
The most influential parameter on seabed instabilities are water wave properties, i.e., wave period, wave length and wave depth. Any change in these parameters will cause a change in the mudline dynamic pressure, which is directly proportional to the instability of the seabed.


[29] W.F. Marcuson, “Definition of terms related to liquefaction”.


