You Cannot Have Your Cake and Eat It, too: How Induced Goal Conflicts Affect Complex Problem Solving

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Abstract: Managing multiple and conflicting goals is a demand typical to both everyday life and complex coordination tasks. Two experiments (N = 111) investigated how goal conflicts affect motivation and cognition in a complex problem-solving paradigm. In Experiment 1, participants dealt with a game-like computer simulation involving a predefined goal relation: Parallel goals were independent, mutually facilitating, or interfering with one another. As expected, goal conflicts entailed lowered motivation and wellbeing. Participants’ understanding of causal effects within the simulation was impaired, too. Behavioral measures of subjects’ interventions support the idea of adaptive, self-regulatory processes: reduced action with growing awareness of the goal conflict and balanced goal pursuit. Experiment 2 endorses the hypotheses of motivation loss and reduced acquisition of system-related knowledge in an extended problem-solving paradigm of four conflicting goals. Impairing effects of goal interference on motivation and wellbeing were found, although less distinct and robust as in Experiment 1. Participants undertook fewer interventions in case of a goal conflict and acquired less knowledge about the system. Formal complexity due to the interconnectedness among goals is discussed as a limiting influence on inferring the problem structure.

Keywords: complex problem solving, goal conflicts, motivation, system knowledge, strategy.

INTRODUCTION

You cannot have your cake and eat it, too. One of the possibly best-known goal conflicts is delivered by a proverb. Similar common sayings across other languages exist, marking conflicting strivings an intercultural or even universal phenomenon. Examples from everyday life are abundant: working overtime in order to qualify for a better job vs. spending leisure time with friends or family, affording either an expensive holiday trip or a redecorated apartment, enrolling to a fitness class vs. watching TV in the evening, just to name a few. From an interpersonal point of view, goal conflicts can be found within the structure of enterprises and organizations. Managers in business and industry, e.g., ought to keep a balance between financial gains, customers' demands, efficient work processes and both sustaining and developing employees' human resources [1]. Multiple goals may arise from the demands of multiple lobbies. They can entail both interpersonal goal conflicts between the lobbies’ members as well as intrapersonal goal conflicts within an ambivalent manager’s mind.

Yet, to pursue multiple and conflicting goals is more than a mere decision on priority, subordinate and dispensable goals. The manager in our example additionally needs to figure out how each of the goals can be achieved. Experience through exploration, analytical and practical skills are necessary to overcome barriers that make the desired state differ from the situation at hand – a prototypical instance of complex problem solving [2].

In the present paper, we investigate how cognitive representations and strategies in problem solving are affected by goal conflicts. Emphasis is put on the interaction between cognition, motivation, and the experience of distress. A complex dynamic control (CDC) task approach is reported and applied in two subsequent experiments.

MULTIPLE GOALS IN COMPLEX PROBLEM SOLVING

Speaking in terms of a general definition, complex problems represent multifaceted, dynamic situations that involve a large number of interconnected elements. The exact, underlying relationships between a problem's components are unknown to the person struggling with the problem. Besides this, the complex problem can be denoted as polythetic (i.e., implying multiple goals): Problem-solvers are confronted with a number of different goal facets to be weighted and coordinated [2].

RELATIONSHIPS AMONG MULTIPLE GOALS

As any given complex problem constitutes a system of connected elements, goals within the problem structure usually do not stand apart, but are linked according to one of three relational types: goal independence, goal compatibility, or goal interference [3]. For dyads of two goals each, the relational types can be defined as follows: In case of goal independence, in spite of interrelated elements in a problem space goals can be pursued and achieved separately from one another. Goal A has no effect, neither positive nor negative,
on goal B and vice versa. Goal compatibility, sometimes
termed goal facilitation or goal synergy, refers to contexts in
which achieving goal A increases the probability of achiev-
ing goal B at the same time. Goal interference – finally and
most interestingly in our study – occurs if two goals cannot
be achieved simultaneously without considerable extra effort
or cannot be achieved simultaneously at all. Successful ac-
tions towards goal A will decrease the probability of reach-
ing goal B as well. Goal interference should occur if both
goals require equivalent, but limited resources (e.g., time,
cognitive capacities) and compete for them as found in mul-
titasking paradigms [4]. Besides such indirect goal conflicts
based on parallel demands, goals can be opposed when their
consequences are mutually exclusive. In an extreme specifi-
cation, goal A would be the precise negative mirror image of
goal B (not-A), making combined success logically impossi-
bile. We will refer to these conflict situations as goal antago-
nism and provide examples in the method section below.

CURRENT STATE OF RESEARCH

In how far has empirical research taken into account the
effects of multiple and conflicting goals? At first glance,
research on goal conflicts appears to be abundant. Beginning
with the work of Kurt Lewin [5] it has been widely recog-
nized that goal conflicts are difficult to deal with. Many is-
ues stemming from Lewin’s tradition are settled in the pri-
mary field of motivational psychology with particular respect
to long-term personal strivings and wellbeing [6, 7]. Em-
mons and colleagues [8, 9] report increased levels of con-
flict-related stress and reduced wellbeing, although under
a certain conditions stabilizing effects of multiple goals on
wellbeing have been observed [10]. Studies from the field of
action psychology and multitasking paradigms [4] explain
reduced performance by limitations of human cognitive ca-
pacity.

Issues focusing on goal conflicts in complex problem
solving, however, are comparably scarce. Firstly, a straight-
forward and well-supported general prediction is that the
more goals are to be handled simultaneously the worse goal
achievement will be. With respect to complex problem
solving, an experiment by Funke [11] is in line with this
view. Participants dealing with four parallel goals in a
CDC simulation performed worse on goal achievement and
acquisition of goal-related knowledge than control subjects
dealing with only two goals in the same complex system.
The effect was observed although no explicit goal antago-
nism was inherent to the problem structure.

Secondly, besides the mere number of goals their quality
has required consideration. A CDC problem-solving exper-
iment by Vollmeyer and Burns [12] provided evidence that
participants instructed to merely explore a CDC system
(unspecified goal) gained more system-related knowledge
than participants instructed to reach specific goal values. As
Vollmeyer and Burns [12, 13] argue, single, specific goals
can promote the acquisition of isolated solution paths, but in
order to gain broad, comprehensive knowledge goal specific-
ity will be less helpful.

AIM OF THE CURRENT STUDY

In the discussion of problem solving under polytelic con-
tions, thus far, some authors have been implicitly assuming
underlying goal conflicts [2], but lacked a closer look at how
problem solvers actually perceive goal relations. The study
at hand aims at a clear separation between multiple goals on
the one hand and conflicting goals on the other hand. Using
the taxonomy presented above, we will investigate effects of
explicit goal antagonism in a formal complex problem-
solving paradigm. Additionally, we will reconsider the im-
 pact of capacity limitations by varying the number of con-
flicting goals in a second study.

HOW GOAL CONFLICTS MIGHT AFFECT COM-
PLEX PROBLEM SOLVING: A FRAMEWORK

The main concern of our study is to combine the above
named perspectives from motivational psychology and the
perspective of complex problem solving. An initial move
towards a cognitive-motivational framework of problem
solving under polytelic situations is developed. Our pioneer
framework includes five hypotheses to be tested (see Fig. 1).

Hypothesis 1: In complex problem situations involving
antagonistic goal relations, problem solvers report losses of
current motivation.

We expect measures of current motivation to decrease in
problem-solving situations of antagonistic structure since
antagonism implies at least partial non-attainment of goals.
Given that two goal states cannot be achieved at the same
time, subjects should be prompted to settle for moderate suc-
cess concerning both goals or they might accept failure for
one goal combined with success for the complementary goal.
Whereas in real life further strategies might be conceived
e.g., striving for one goal first and for the other goal next,
trying to find common aspects to link both goals on a con-
ceptual level), according to our understanding of goal an-
tagonism, goal redefinitions are limited. Disappointment is
therefore pre-assigned in either case, independent of individu-
ual goal management.

The feasible assumption that goal failure induces low
motivation finds empirical support for both long-term striv-
ings and relatively straightforward achievement tasks in ex-
perimenal settings (e.g., [14-16]). Mediated by pre-installed
(partial) failure, participants should suffer from losses in
current motivation.

Hypothesis 2: In complex problem situations involving
antagonistic goal relations, problem solvers report increases
in experienced stress symptoms.

Similar to hypothesis 1, we assume that in addition to
supposed motivational effects subjective wellbeing including
physiological symptoms, too, will be impaired for situations
of conflicting goals. We predict increased rumination about
non-attainment, depressive mood, and perceived stress
[17].

Hypothesis 3: In complex problem situations involving
antagonistic goal relations, problem solvers adopt a deliber-
ate, state-orientation-like approach towards the problem.

Rumination associated with depressive mood can be con-
sidered as a specific cognitive style. When struggling with
non-attainable and non-attained goal standards, frustrated
problem-solvers should be less prone to undertake immedi-
ate measurements of exploration or goal-directed problem
solving. By the conflicting goal structure, action is more or
Fig. (1). A cognitive-motivational model of goal conflicts’ effects on complex problem solving.

less obstructed. Instead, problem-solvers are likely to spend more time thinking about possible reasons for failure and trying to figure out alternative measures.

**Hypothesis 4**: In complex problem situations involving antagonistic goal relations, problem solvers adopt increased systematics of manipulation strategies.

The question arising from previous hypotheses is whether presumed rumination, state-orientation and negative affect will be attended by low efficiency in problem solving. We suggest that this is not the case. Research on interactions between mood and cognition provides theoretical reasoning and empirical support that in a negative mood people tend to perform worse on heuristic, creative tasks, but better on tasks demanding accuracy and analytical reasoning [18]. Although problem solving implies creativity, analytical thinking, too, is necessary to exploration and comprehensive understanding of the problem-structure. In most analytical problems the quality of a solution will benefit from thorough reflection and from a scarce number of subjects’ interventions [13, 19-23]. The less interventions are undertaken, the more knowledge will be gained, i.e., the better a complex system will be decoded in terms of its various, interconnected effects, because problem-solvers have the chance to observe and infer effects separately, one after the other. Accordingly, states of limited action-orientation appear to entail useful, systematic, and purposeful strategies of dealing with a complex system, and these strategies are expected to accumulate under goal conflict conditions.

**Hypothesis 5**: In complex problem situations involving antagonistic goal relations, problem solvers acquire an increased amount of system-related knowledge.

Systematics of exploratory strategies predicts how well a person will figure out the problem structure [12, 21]. This positive relationship makes us assume increased knowledge acquisition when goal conflicts occur than when goals are compatible, the relational complexity of the system being kept constant.

**A CDC TASK APPROACH TO INDUCE GOAL CONFLICTS**

As outlined in the section of goal relations, goal conflicts can arise from multiple origins. Multitasking-like scenarios usually imply goal conflicts because time constraints or limitations in cognitive capacity force a person to abandon goals or subgoals [4]. However, they do not guarantee conflicts, and the degree of conflict may vary with an individual’s skill, ability, and experience. To lessen the impact of interpersonal differences and to ensure that conflicts will definitely occur we decided in favor of a direct conflict manipulation implemented in a computer program. The basic notion is to design a goal relation so that the closer a person gets to reach one goal, the more he or she will drift away from another, conflicting goal.

**Semantic Context of the CDC Task**

We aimed to create a quasi-realistic simulation environment that incorporates an antagonistic goal structure in a motivating semantic goal context. According to the cover story we chose, our simulation tool, the “Hanssen Shipping Company”, provides a simplified version of a virtual business environment. Participants are assigned the part of the ship owner and leading entrepreneur. In doing so they simultaneously strive for each of the four goals: (a) contentment of passengers, (b) productivity of employees, (c) quality of management, and (d) public reputation of ship owner. Theoretical foundation of this goal structure is derived from the management concept of the Balanced Score Card [1].

A semantic pretest was conducted to figure out whether on the base of their general “world knowledge” people would expect conflict relations between any of these goals. An online questionnaire was completed by a mixed sample of students and shipping experts (N = 45). On average, participants rated the goal relations neutral, i.e., neither conflicting nor synergistic. We therefore concluded that from their pre-experimental knowledge subjects should find it about equally likely to discover either conflict, independence or synergy between dyads of the scenario goals.

Each of the four goals are associated with nine corresponding measures, which, when activated, directly affect a goal (for examples see Fig. 2 below). In order to improve the contentment of passengers, participants can, e.g., extend the animation aboard, enlarge the service team in a traveling agency, or reduce traveling fares; in order to improve the productivity of employees, participants can try to reduce the amount of routine demands, introduce flexible working hours, or renovate the staff canteen, among others. These measures, too, were pre-rated in the online questionnaire according to two criteria: (a) for which category the measure was most typical and (b) how effective each measure was...
considered with respect to promoting the corresponding goal. Averaged effectiveness ratings provided the basis of effectiveness parameters implemented in the computer program.

**Structure of the CDC Task**

The variables from our list that can be manipulated by the participant are called the input or exogenous variables. The two-goal version of our scenario (Experiment 1) involves 18 such variables, the extended four-goal scenario (Experiment 2) involves 36 exogenous variables. Endogenous variables are the two goal variables contentment of passengers and productivity of employees in Experiment 1 and the four goal variables contentment of passengers (CP), productivity of employees (PE), quality of management, and public reputation of ship owner in Experiment 2. For illustration, we describe the conflict manipulation between two goals in detail. For a description of the four-goal version see the method section of Experiment 2.

Being a dynamic problem, the CDC task consists of a sequence of intervention steps. Problem solvers choose measures from the lists, i.e., they make interventions, which in turn are followed by a feedback of the system and then by the participant’s next intervention. The system provides feedback as numerical scores of the endogenous variables, starting with the default value of 100 at the outset. The higher the score, the more successful the goal attainment.

Exogenous variables affect the endogenous scores as follows: Each input variable has been assigned a defined, numerical weight, i.e., its effectiveness. A highly effective measure such as “increase payment of wages” would yield a weight of 4 points, a moderately effective measure such as “renovate staff canteen” would yield a weight of 2 points, and a non-effective measure such as “apply recruitment tests” would yield a weight of 0 points. Among the nine exogenous variables associated with a goal, there are three variables from each category. For all exogenous variables chosen during an intervention step, the corresponding weight scores will be summed up. In order to prevent that subjects simply pick all exogenous variables, cost scores will be subtracted. Costs are implemented so that selecting the full range of interventions will neither yield an increase nor a decrease in the goal scores. Instead, to raise goal scores, participants are challenged to experiment and search for effective single or combined measures from the intervention list. Also, if a particular – and particularly effective – combination of inputs is selected, a predefined bonus score will be added. Picking the three highly effective measures “increase payment of wages”, “send machine operators on advanced training courses”, and “award bonuses for special achievements” on the side of PE and none but these, e.g., will be rewarded by 12 extra scores.

Weight scores, bonuses and costs will be totaled to form an intervention score which directly relates to an endogenous variable. If the current score of CP has been 100 and 12 points have been gained due to manipulations listed under CP, the next step’s score of CP will be 100 + 12 = 112. Similarly, if the current state of PE has been 100 and 4 points have been gained due to manipulations listed under PE, the next step’s score of PE will be 100 + 4 = 100. So far, this example illustrates an independent goal relation. To turn it into a conflict relation, points gained on the part of CP will be subtracted from the total score of PE and vice versa, e.g., as to CP 100 + 12 − 4 = 108 and as to PE 100 + 4 − 12 = 92. This implies that for antagonistic goals in the approach at hand, in fact, the sum score of both goals will maintain a constant level. Gains regarding the goal CP can only be realized at the expense of equally large losses concerning the goal PE.

Besides this manipulation of an immanent goal conflict (goal antagonism), for the purpose of between-subjects comparisons in the experimental design we established a version of the above explained goal independence and a goal synergy version. Goal synergy implies the same degree of formal complexity as goal antagonisms, but instead of subtracting, points gained on either side are added to both goals. Following the example this would lead to a score of 100 + 12 + 4 = 116 for CP and an equal score of 100 + 4 + 12 = 112 for PE.

**EXPERIMENT 1**

**Method**

Participants. 69 participants (15 male, 54 female) were recruited at the Department of Psychology at the University of Heidelberg, Germany. Most subjects were undergraduate students in psychology, ranging in age from 18 to 45 (M = 22.35, SD = 5.14). To compensate for participation, students were given course credit. For two participants, electronic recording of problem-solving activities partly failed. To ensure balanced three-level ANOVA analyses, from a random observation of the third experimental condition we removed corresponding data, leading to sixty-six complete data records (22 per goal condition). Gender ratios were equal for the three experimental conditions.

**Design**. Goal relation was manipulated between subjects on three levels: goal antagonism, goal independence, and goal synergy. Participants worked on the goal scenario for two identical and subsequent rounds; “time” was hence introduced as a two-level within-subject-factor in a 2 × 3 ANOVA design.

**Procedure**. After a brief outline of the experimental procedure, by signature subjects gave their informed written consent to participate. They were reminded that taking part was voluntary and that they might abandon the experiment if they wished to. Instruction phase furthermore comprised a questionnaire on self-regulatory habits (HAKEMP), an introduction on how to handle the computer simulation, and self-report questionnaires on pre-experimental stress and current motivation. Subjects passed through two phases of complex problem solving, each consisting of a ten-step-interaction with the CDC task and afterwards questionnaires on system-related knowledge, self-reported strategic approaches, stress, and current motivation. Goal relation was randomized between subjects, i.e., one third of the sample worked on an antagonistic goal scenario, one third on an independent goal scenario, another third on a synergistic goal scenario. The goal relation assigned to a participant remained the same throughout the two phases. Final measures on socio-demographical variables and school achieve-
Subjects were debriefed concerning the purpose of the study and received course credit and chocolate in return for their services.

**Materials and measures.** The “Hanssen Shipping Company” simulation was created with the aid of the programming tool AgentSheets, version 1.6 X [24]. Subject data were written automatically into MS excel files while running the system. A screenshot of the two-goal-scenario is provided by Fig. (2). Labels are translated into English. The original version employed in our experiment contained German labels. All information necessary to work on the problem is compiled in one window. The upper part displays achievement status for both goal demands by score numbers, horizontal bars represent the score graphically, and arrows indicate either an upward, downward, or a constant development of goal scores. From the lists below, users point and click boxes to select or deselect relevant measurements by visible check marks. Once they have finished they submit their inputs by operating the “finished” button, then switching to a new simulation month, i.e., a new intervention step. Check marks from the previous month are then removed. Participants run through a sequence of ten such independent steps. From the instruction participants were encouraged to start their exploration on the base of pre-existing knowledge and plausibility. Yet they were clearly pointed to the fact that semantic relations in the scenario might dissent from their individual expectancies and that it might be indicated to modify one’s problem-solving behavior accordingly.

To assess task-related [current motivation](https://www.tandfonline.com/doi/abs/10.1080/17449665.2010.521557) we employed the German version of the questionnaire of current motivation (QCM) developed by Rheinberg, Vollmeyer, and Burns [25]. The QCM form contains 18 statements to appraise on a 7-point Likert scale. Sample items from the QCM are, e.g., “I would work on this task even in my free time” (interest), “I think I am up to the difficulty of the task” (probability of success), or “I feel under pressure to do this task well” (anxiety).

**Experienced stress symptoms** were retrieved by 12 items of a self-report 7-point Likert scale that was constructed from dimensions of perceived stress symptoms according to Kohli [26], e.g., strain, resignation, impatience, anger, restlessness.

Another 10-item self-report questionnaire (5-point Likert scale) asked about styles of subjects’ intervening manipulations. Construction of this measure followed a scale of habitual decision-making styles by Scott and Bruce [27]. Ratings concerning perceived rationality (“I reflected each step carefully”), avoiding decisions (“Often I hesitated because I could not make a decision”), intuition (“Often I decided by intuition”), dependency from others (“I would have liked to ask somebody for advice”), and spontaneity (“Most of the time I decided spontaneously”) were combined to describe cognitive approaches towards the problem. For the same purpose we recorded and analyzed solution times.

**Systematics of manipulation strategies** was inferred from the number and ratio of chosen interventions. Low mean intervention frequencies were labeled systematic. An index of balanced vs. imbalanced intervention approaches was calculated as follows: number of interventions corresponding to goal A minus number of interventions corresponding to goal B.
B for intervention step \( t \). The mean absolute value of these differences averaged above ten steps yielded the balance index. Low scores indicate a balance-focused strategy.

As a test of acquired system-related knowledge subjects completed an assessment questionnaire about the intervention list. They rated each intervention according to how it affects both the first and the second goal. Ratings employ a 5-point scale from supposed advantageous effects to supposed disadvantageous effects. An index of acquisition of system-related knowledge was calculated by comparing subjects’ responses to the preset impact categories and by accounting for antagonistic or synergistic goal relations. Perfect ratings were scored 1, ratings from suboptimal, but adjacent categories were scored zero, ratings differing two or more categories from the preset value were punished by minus one score.

For purposes of experimental control and additional testing we recorded subjects’ age, sex, profession or field of study. As an approximate indicator of cognitive ability final school exam grades (overall grade and math grade in particular) were surveyed. Motivational personality habits of action orientation or state orientation were raised by means of Kuhl’s questionnaire on action-control HAKEMP [28]. Analyses concerning these variables yet yielded no significant effects and will not be reported for the sake of brevity.

Results

Motivation and Stress. After factor analytical exploration of self-report data (PCA, varimax rotation), from QCM items two 9-item subscales were generated that corresponded to the combined QCM subscales “anxiety – probability of success” (AP) and “interest – challenge” (IC) from the original QCM [25]. Concerning pre-experimental motivation, participants of the three experimental conditions showed comparable levels of AP and IC: AP: \( F(2, 68) < 1, ns \); IC: \( F(2, 68) < 1, ns \). For AP measured after Phase 1 and 2, there was a significant main effect for goal relation, \( F(2, 66) = 6.56, p < .01 \), indicating lower expectancy of success for participants of the antagonistic goal condition as compared to the two control groups (\( p < .01 \)). However, no such effect occurred for IC, \( F(2, 66) < 1, ns \).

The stress scale was reduced to a 10-item one-dimensional scale with Cronbach’s alpha internal consistencies between alpha = .83 (pre-experimental) and alpha = .86 (after Phase 1). As with motivation, no significant effects prior to simulation experience were found, \( F(2, 67) < 1, ns \). In Phase 1 and 2, however, a significant main effect occurred, \( F(2, 65) = 4.84, p < .05 \), \( f = 0.39 \). Post hoc contrasts revealed that perceived stress was significantly higher in the antagonistic goal condition (\( p < .01 \)).

Overall, participants rated their probability of success relatively high. Mean ratings ranged from \( M = 5.52 \) (SD = .13; pre-experimental) to \( M = 5.73 \) (SD = .11; Phase 2) on a 7-point scale with an upward tendency over time. Pillai’s Trace: \( F(2, 65) = 5.70, p < .01 \), \( f = 0.42 \). Stress levels in the experimental testing situation were constantly low over experimental conditions, with mean scores between \( M = 2.39 \) (SD = .81; Phase 2) and \( M = 2.55 \) (SD = .86; pre-experimental) on a 7-point scale, Pillai’s Trace: \( F(2, 64) = 1.32, p = .28 \).

Cognitive style. Self-reports from the questionnaire of cognitive approaches in problem solving were analyzed according to two sub-dimensions gained from factor analysis (PCA, varimax rotation): systematic vs. heuristic style (6 items) and dependent-hesitant vs. assertive style (4 items). Typical items to characterize the systematic style were “I reflected on each step carefully” (systematic style) or “Often I decided by intuition” (heuristic style). The dependent-hesitant comprises items such as “Often I hesitated because I could not make a decision” (hesitant style) or “I would have liked to ask somebody for advice” (dependent style). The total variance explained by the two-factor solution was 46.83 % for Phase 1 and 58.70 % for Phase 2. For both subscales measures of internal consistency were satisfactory. Means of reported systematic styles did not vary significantly among groups, \( F(2, 66) < 1, ns \). However, for the dependency scale effects of goal relation became highly significant, \( F(2, 66) = 7.49, p < .01 \), \( f = 0.48 \). This was due to higher ratings among participants of the goal conflict condition (\( p < .01 \)). Reported dependency and hesitation within all groups markedly declined over time, i.e., problem-solvers became more assertive with growing experience, \( F(1, 66) = 10.90, p < .01 \), \( f = 0.41 \).

As behavioral measurements of hesitation we investigated mean solution times. These, too, showed a decline over time, reflecting effects of experience and habituation, \( F(1, 66) = 111.91, p < .01 \), \( f = 1.30 \). Yet we did not detect any differences attributable to goal condition, \( F(66, 2) = 1.01, p = .37 \). On a descriptive level, subjects dealing with the synergistic scenario spend the least time on the problem (\( M = 29.27, SD = 2.80 \)) while on average subjects of the antagonistic (\( M = 34.11, SD = 2.80 \)) and the independent goal group (\( M = 34.17, SD = 2.80 \)) required virtually the same length of time.

Not quite consistently, there were positive relations between solution time and self-reported dependency. The higher perceived hesitation, the longer the time spent on the corresponding round of problem solving. Correlations were of moderate, but robust size, with coefficients of \( r = .46 \) for Phase 1 and \( r = .34 \) for Phase 2.

Problem-solving strategies. According to our hypothesis, for the antagonistic goal relation scenario, overall, we had assumed a reduction of selected interventions. This general prediction was not confirmed (Phase 1: \( \chi(2) = 2.35, p = .31 \), Phase 2: \( \chi(2) = 1.08, p = .58 \)). In fact, subjects of the antagonistic goal condition performed more interventions in Phase 1, but fewer interventions in Phase 2 than did control subjects (see Fig. 3). Control participants, on average, kept a constant level of system manipulations. This observation was tested statistically by comparing the pairwise differences of intervention scores from Phase 1 minus Phase 2. A highly significant Kruskal-Wallis test indicated that the differences were considerably higher under goal antagonism (\( \chi(2) = 17.66, p < .01 \)). Hence, an interaction between time as a within-subject-factor and goal relation as a between-subject factor was identified.

The pattern of starting with strong manipulation in Phase 1 and weak manipulation in Phase 2 was observed not only with regard to between-subject effects, but also in an exploratory within-subject analysis. We divided subjects in two categories: those whose mean intervention score decreased
from round 1 to round 2 and those whose mean intervention score either increased or remained equal. Nearly all of the antagonistic goal participants were found to belong to the first category. In contrast, among independent and synergistic goal participants classification ratios appeared to be balanced, $\chi^2(2) = 15.56, p < .01$.

With respect to the second indicator of problem-solving strategies, intervention balance, our hypothesis predicted a more balanced manipulation behavior in case of antagonistic goals. We assumed that problem-solvers would equally mind the two goals and undertake about equal numbers of intervention on each side. However, results showed the reverse: Imbalance was significantly higher in antagonistic scenario treatment ($p < .05, f = 0.38$). Closer analysis revealed that effects of raised imbalance only occurred in Phase 1, $F(2, 66) = 7.47, p < .01, f = 0.48$, but not in Phase 2, $F(2, 66) < 1, ns$. Hence, subjects confronted with antagonism started by using a rather imbalanced approach and tended to keep more balance later. Control participants on the contrary began their exploration balanced and prioritized goal handling later.

Taken the results together, no increased systematics according to the conventional view appeared. Yet the two indicators of strategy employment convey an adaptive pattern of self-regulatory processes in dealing with conflict problems. “Overreaction”, i.e., overregulation and intensified measures may be the initial response to cope with a difficult and frustrating antagonistic problem. In our first experiment reduced intervention was identified as late as in Phase 2, i.e., after some experience and possibly after a change in strategic approach.

**Acquisition of system-related knowledge.** Fig. (4) displays the indices of mean knowledge acquisition over Phase 1 and 2 related to experimental conditions. A highly significant main effect for goal relation appeared, $F(2, 66) = 16.34, p < .01, f = 0.70$. This was assignable to the immense amount of knowledge gained under independent goal conditions ($p < .01$). Comparing the two scenarios of equal connectedness, i.e., the antagonistic goal condition versus the synergistic condition, contrary to our expectation there were no meaningful differences ($p > .50$). The within subject-factor time proved significant and thus hinted at effects of learning and experience on understanding the unknown effects of interventions on goal states, $F(1, 66) = 5.77, p < .05$.

**Discussion**

Based on a cognitive-motivational framework we stated a number of characteristic effects occurring when complex problem-solving situations involve conflicting goals. Firstly, we argued that problem solvers’ current motivation would suffer from conflict experience as well as perceived stress levels would increase. The results support these assumptions although, considered from an absolute level, subjects still seemed confident and relaxed in spite of the preset goal conflicts. The finding is much in line with the well-documented everyday phenomenon that failing to reach goals or perceiving stagnation in planned transactions leads to frustration and stress [17, 29].

Yet the more difficult, potentially frustrating tasks are not necessarily the more boring ones according to participants’ ratings. No systematic interrelation between goal type and the combined scale of interest and challenge was found. General and more obvious features of appearance and usability might have influenced interest in the computer system than did the structural differences between experimental conditions. Furthermore, personality factors may have a
great impact on this matter. From the perspective of personality, interest should depend on both a problem-solver’s ability as well as on habitual preferences for difficult or simple ventures as related to achievement motivation [30]. In this case, however, indirect indicators of ability (school grades) turned out to be non-predictive.

Another expected characteristic of problem solving under antagonistic goal conditions was a passive, state-orientation like approach in handling the simulation scenario. This hypothesis turned out to fit with self-report data of hesitation and perceived feelings of dependency, but not with the objective amount of time spent on the task. As both indicators correlate positively, to some extent solution times tend to be affected by goal conflicts, too. But we presume that measurable solution time is no perfect mapping of hesitation and insecurity. During problem-solving subjects may slow down for a variety of reasons both related and unrelated to the problem at hand. For those who feel unassertive how to cope with the problem ruminations and extended reflection time is simply one possible strategy among others. An alternative, e.g., would be to rush through the task, realizing that most effort in the conflict scenario will remain without substantial effect anyway. Thus, by analyzing mere solution times no insight is provided in whether problem-solving actions are constructive, reflective, and efficient or panic-like, non-reflective, and inefficient.

Cognitive indicators of problem solving in a narrower sense were observable strategies and knowledge acquisition. Results concerning the number and balance of selected interventions promote the idea that preset goal conflicts induce different types of strategies than do problems of multiple, independent goals. Against expectations, however, strategies appeared to be instable and showed dynamic variations over time. As a general trend averaged over participants and intervention episodes we observed a pattern of initial “actionism” and later intervention reduction. Paralleling this effect, subjects dealing with goal antagonism started with rather imbalanced manipulation patterns, i.e., they tended to promote the more deficient goal module and to ignore the other – until in the following step the formerly ignored module was deficient and had to be pushed. As the number of manipulations decreased over time, on the whole problem-solving strategies became more balanced and represent simultaneous pursuit of the two demanded goals. These specific changes did not appear when goals were independent or synergetically related.

Considering knowledge acquisition, successfully grasping the problem structure turned out to be a matter of the system’s formal complexity or connectivity [11, 31, 32]. Subjects analyzed the system best and found out most correct information if parallel goals were unrelated. Obviously, testing the effects of single interventions is much easier if nine intervention measures contribute to influence a goal score than if the goal score is influenced by nine plus nine intervention measures. The hypothesis according to which goal antagonism drives problem-solvers to systematic, efficient acquisition of structural knowledge must be deferred because in spite of equal degrees of formal complexity, antagonistic goal subjects did not understand the sysem any better than their peers from the second control group, the synergistic goal condition.

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**Fig. (4).** Reproduction of participants’ acquired system-related knowledge in Experiment 1 \( N = 69 \).

![Graph showing the reproduction of participants' acquired system-related knowledge in Experiment 1.](image-url)
To summarize, in Experiment 1 induced goal conflicts had temporary, but verifiable effects on motivational and cognitive facets in the process of complex problem solving. Namely, conflict experience impaired expectations of success, enhanced insecurity and stress. Problem-solving strategies can be characterized as a crossover from enhanced action to low, but possibly more thoughtful action. Knowledge acquisition does not benefit from antagonistic structures in a complex scenario. Instead, it is important to stress that goal conflicts are generally associated with intransparency and complexity, which complicates the process of gaining knowledge.

Experiment 2 was conducted to test whether the main findings could be generalized in a multiple goal setting involving more than two goals. The aim was to replicate motivational effects of goal antagonism and to justify post hoc explanations concerning self-regulative strategies on an independent data basis.

EXPERIMENT 2

Method

Participants. We tested 42 subjects (15 male, 27 female) who had not taken part in the first study and hence had no prior experience with the shipping scenario. In the sample, students of different fields of study were included (psychology, natural sciences, humanities, law, economics, and social sciences). 17 students (40%) were enrolled in psychology. We assessed prior experience with the shipping scenario. In the sample, who had not taken part in the first study and hence had no prior experience with the shipping scenario. In the sample, who had not taken part in the first study and hence had no prior experience with the shipping scenario.

Design. Only two levels of goal relation were tested in a between-subject design: goal antagonism vs. goal independence. Measures from two identical rounds of problem solving led to time as a within-subject factor in a 2 × 2 ANOVA design.

Procedure. The course of experimental procedure was virtually the same as in Experiment 1: introductory phase, two rounds of scenario treatment followed by final recordings and debriefing.

Materials and measures. The main novelty of Experiment 2 concerned the construction of the CDC task. Antagonistic goal relations were established between the four, pre-tested goal demands. Antagonism followed a circular structure, i.e., in the conflict condition intervention scores of the goal contentment of passengers were subtracted from the quality of management scores, quality of management negatively affected the public reputation of the ship owner, ship owner’s reputation negatively affected the productivity of employees and this, in turn, exerted antagonism on the contentment of passengers. In the extended version of “Hanssen Shipping Company” the four goal states and related measure lists were presented simultaneously on a single screen. As in Experiment 1, each round comprised ten intervention steps.

Measures of current motivation, experienced stress symptoms, cognitive solution approaches, and acquired system-related knowledge were adopted from Experiment 1. Regarding intervention balance, instead of the difference algorithm, we computed the variation of intervention frequencies per goal over the four goals of the same intervention step. These were averaged above the ten steps per round. High average variation scores are interpretable in terms of an imbalanced procedure whereas low variation reflects more balanced approaches.

Results

Motivation and stress. The two-factor FAM measures AP and IC as well as the 10-item perceived stress scale from Experiment 1 were confirmed and adopted. Pre-experimental differences were found neither for the AP and IC motivational subscales nor for the stress scale, AP: t(40) = .07, ns, IC: t(40) = 1.33, p = .20, stress: t(40) = 1.70, p = .10. Contrary to our expectations and first findings, repeated measures over Phase 1 and 2 yielded no significant effects of motivation although AP and IC tended to be lower in the antagonistic goal condition, AP: F(1, 40) = 2.81, p = .10, IC: F(1, 40) = 1.75, p = .19. Comparisons of stress means over Phase 1 and 2 reached marginal significance in the predicted direction, F(1, 40) = 3.99, p = .05. The effect was more prominent for Phase 1, i.e., after subjects’ initial confrontation with the conflict scenario, than after Phase 2.

In line with the previous results, mean ratings of AP above three measuring times ranged from M = 5.62 (SD = .18) to M = 5.68 (SD = .16). Stress ratings ranged from M = 2.75 (SD = .19) to M = 2.93 (SD = .21). In brief, participants were relatively confident and relaxed in mastering the simulation problem with a tendency of impairment when goal conflicts existed.

Cognitive style. The two studied self-report dimensions, systematicity and dependency – hesitation, were the same as in the first experiment. As only dependency proved sufficiently stable in the check of internal consistency, the systematicity scale was omitted. For self-reported dependency, a significant main effect of goal relation was found, F(1, 40) = 6.43, p < .05, f = 0.40. As predicted, subjects of the antagonistic goal condition rated perceived hesitation higher. Once again, no corresponding effect of solution time occurred, F(1, 40) < 1, ns. Hesitation tended to decrease over time although not significantly, F(1, 40) = 2.37, p = .13. Concerning solution times the effect of customization was highly prominent, F(1, 40) = 121.09, p < .01, f = 1.74.

Problem-solving strategies. In line with our original hypothesis, but partly differing from the first study, in Experiment 2 we identified significantly lower intervention frequencies in the antagonistic goal condition than in the independent goal condition. The findings refer to both Phase 1 and Phase 2 (Phase 1: U = 110.00, p < .01, Phase 2: U = 85.00, p < .01). Subjects dealing with the antagonistic problem started on a low intervention level and reduced manipulation frequencies even further. Subjects of the independent goal condition showed but a slight decline in manipulation frequencies on a higher starting level (see Fig. 5). Corroborating prior interaction results, the decline over time was significantly more pronounced when goals interfered than when they were independent (U = 136.50, p < .05).

The index of imbalanced problem-solving behavior did not turn out to differ significantly between the two experimental conditions (Phase 1: U = 165.00, p = .34, Phase 2:
As found in Experiment 1, the difference between the Phase 1 variation score and the Phase 2 variation score was higher for antagonistic goal condition subjects, i.e., only these participants inclined towards a more balanced approach. Yet statistics did not firm up descriptive observations (U = 184.00, p > .50).

**Acquisition of system-related knowledge.** Subjects of the more complex experimental conflict condition performed worse on the knowledge test than did their peers of the independent goal condition, \( F(1, 40) = 18.67, p < .01, f = 0.68 \).

**Combining and Comparing the Results from Experiment 1 and Experiment 2**

An additional issue approached the question of how the number of preset goals in a complex problem-solving paradigm affects motivation and cognition. Analyses are based on a merged sample of subjects from Experiment 1 and 2. Only participants of the antagonistic and the independent goal condition were included, leading to a total sample size of \( N = 88 \). The three two-level factors goal number (two vs. four), goal relation (antagonistic vs. independent) and time make up a nearly balanced, quasi-experimental \( 2 \times 2 \times 2 \) ANOVA design with cell sizes of either \( N = 21 \) or \( N = 23 \) and repeated measures.

Dependent variables to be examined were the following: the motivational scales anxiety – probability of success and interest – challenge, stress, solution time and reported dependency. For none of these variables interactions between goal number and goal relation were found. Main effects of goal relation conform to those from single-experiment analyses. The factor goal number reached significance for the IC scale, \( F(1, 84) = 7.89, p < .01, f = 0.31 \), and for solution time, \( F(1, 84) = 65.98, p < .01, f = 0.89 \). Subjects working on the extended four-goal scenario rated the task more interesting and spent almost twice as much time on it. On average, participants in Experiment 1 took \( M = 34.14 \text{ s} \ (SD = 2.39) \) per intervention step, whereas participants in Experiment 2 took \( M = 62.25 \text{ s} \ (SD = 2.50) \). No differences occurred with regard to self-assessments of probability of success, \( F(1, 84) < 1, ns \), stress symptoms, \( F(1, 84) < 1, ns \), and hesitation, \( F(1, 84) < 1, ns \).

**Discussion**

Experiment 2 reinvestigated the cognitive-motivational model of goal antagonism in complex problem-solving in the context of four instead of two conflicting goals. Impairing effects of goal interference on motivation and wellbeing were not as distinct and robust as in the first study. They tended to last but for the first of two rounds in working on the computer simulation. Possibly, as the four-goal scenario contained twice as many intervention measures than the two-goal scenario, this task was rather complicated even in case of goal independence, and discriminatory power due to the goal relation factor was reduced. Some participants under the goal conflict condition noted they knew declining goal scores were “not their own fault” and remained unimpressed by the computer’s negative feedback on control performance. A closer look at processes of attribution might be helpful for future investigations.

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**Fig. (5).** Mean intervention frequencies as indicators of strategic approaches in problem solving in Experiment 2 (\( N = 42 \)). The maximum number of selectable interventions was 36.
Concerning strategy employment the results convey a partly ambivalent picture. Based on the enlarged four-goal-scenario they confirm our new, adopted assumption that conflict experience is followed by reduced intervention engagement. Yet initial overregulation, i.e., enhanced manipulation of the system was not observed. One explanation might be that with the extended list of intervention measures, in either treatment condition it was evident right from the beginning that ten intervention steps would be insufficient to test each single measure step by step. So both antagonistic and independent goal problem-solvers might have started with a rather broad, heuristic selection of possibly efficient manipulations.

The relation between goal interdependency and gained structural knowledge about the system was clearly as predicted: The independent goal scenario seems to facilitate analytical reasoning about interventions’ effectiveness. Subjects gave more correct ratings of interventions’ effectiveness. The hypothesis that formal complexity due to intransparency and connectivity is a major determinant on performance in complex problem solving finds further empirical support.

Comparative analyses of Experiment 1 and 2 show that when confronted with four instead of two goal demands problem-solvers’ motivation, wellbeing, and cognitive-behavioral performance is not affected in a negative way. On the contrary, interest is raised. Problem-solvers seemed to find it challenging handling four goals simultaneously, and they accepted the challenge as their long solution times suggest. Generally speaking of a manageable number of parallel goals, a major motivational loss does not result from a struggle for limited cognitive resources, but from difficulties in arranging goals with mutually exclusive consequences. As long as four goals in a computer simulation are concerned, limitations of cognitive capacity cannot offer sufficient explanation for the reported findings. To investigate how many parallel goals will entail capacity overload and concomitant factors, however, can broaden the perspective of research on goal conflicts in the future.

**GENERAL DISCUSSION AND CONCLUSIONS**

The aim of the reported study was to examine motivational and cognitive effects of conflicting goals or strivings. Goal conflicts are well known, universalized phenomena experienced in both group interactions and intra-individual struggling. Our work focused on the intra-individual perspective with particular regard to new, non-routine situations in which an existing incongruity between goals must be detected and managed. Although empirical research has reliably shown motivational impairment of long-term conflict experience (e.g., [9]) the specific approach to problem solving is a new one. Thus far, in the domain of complex-problem solving systematic investigations on polytely have been scarce. As a tool of experimental manipulation and control of goal conflicts we applied a complex dynamic control task, an engaging, game-like computer simulation in which approaching one goal could be performed but at the expense of falling short of another goal.

The results of two studies (\(N = 111\)) support the notion that even in a standardized laboratory setting goal conflicts can be induced. These conflicts lessen motivation during the process of complex problem solving. Reduced confidence in success, impaired wellbeing and increased hesitation are measurable consequences. The findings fit well with the first three out of the five hypotheses we propose in our above framework.

Yet from our experiments there is no evidence that conflict-induced motivational losses strongly affect cognitive problem-solving performance in a linear predictable manner. On a descriptive level we can infer that people becoming gradually aware of a goal conflict react to this awareness in some way. They reveal changed patterns of exploration strategies. Namely, as a generalized trend they will increase action initially. With growing experience manipulations will decrease. Paralleling this effect, problem-solvers will be inclined to try a balanced pursuit of the incompatible goals. In the present studies manipulation patterns were only observed on the base of aggregated data, i.e., effects averaged over experimental treatment conditions and time steps. Extended individual process analyses including think aloud protocols and time-series designs might yield more precise patterns. These in turn would help to refine the strategy hypothesis in our framework as well as the hypothesis of knowledge acquisition.

Our experimental work did not confirm the idea that demotivated problem solvers who are struggling with induced goal conflicts can analyze and reproduce formal relationships within the structure of a complex scenario any better or worse than do relaxed, motivated participants of a control condition as long as the degree of formal complexity is identical. To reinvestigate this fifth hypothesis of the framework it might be necessary to extend subjects’ exploration opportunities. In order to systematically test for effects of single manipulations the number of exploration trials should be increased possibly in combination with less intervention measures to be selected.

Hence, overall there is empirical evidence supporting the framework, but connections between motivational and cognitive effects of goal conflicts will need further inspection. Although the high impact of motivation and cognition or learning has frequently been stressed in research [21, 33] two general concerns can make it difficult to establish strong relations in an experimental paradigm. Firstly, conflict experience does not refer to personal, intrinsic goals. Brunstein and Maier [6] argue that prescribed “told-to-do” goals, too, are prone to arouse conflict, still an experimental induction cannot claim that goal conflicts are deeply grounded in problem-solvers hearts and minds. Secondly, in some cases, simulated conflicts might simply appear interesting and appealing to problem solvers, but not threatening, similar to entertaining polytelic computer games. Our approach was clearly an experimental one, emphasizing differences between treatment groups instead of personality effects. By realizing equal gender ratios among goal relation conditions, the predominance of female participants in our sample still allowed for internal validity. Gender-related styles in goal management, however, might be an issue to be studied in larger samples with equal gender distributions.

In developing the framework of multiple goal effects further we also suggest to take into account the number of conflicting goals. Our exploratory investigation reveals that conflicts between two goals are no less demotivating than
Goal Conflicts in Complex Problem Solving


